

Document code: MN67E00_ENG Revision 1.000 Page 1 of 33

User Manual

Revision 1.000 English

EtherCAT / Serial - Converter

(Order Code: HD67E00-2-A1, HD67E00-5-A1)

For Website information:

www.adfweb.com?Product=HD67E00

For Price information:

www.adfweb.com?Price=HD67E00-2-A1 www.adfweb.com?Price=HD67E00-5-A1

Benefits and Main Features:

- Very easy to configure
- Triple Electrical isolation
- ◆ Temperature range: -40°C/+85°C (-40°F/+185°F)



For other EtherCAT Slave products see also the following link:

Converter EtherCAT Slave to

www.adfweb.com?Product=HD67E01 www.adfweb.com?Product=HD67E02 www.adfweb.com?Product=HD67E03 www.adfweb.com?Product=HD67E04 www.adfweb.com?Product=HD67E05 www.adfweb.com?Product=HD67E06 www.adfweb.com?Product=HD67E07 www.adfweb.com?Product=HD67E08 www.adfweb.com?Product=HD67E09 www.adfweb.com?Product=HD67E10 www.adfweb.com?Product=HD67E11 www.adfweb.com?Product=HD67E12 www.adfweb.com?Product=HD67E14 www.adfweb.com?Product=HD67E15 www.adfweb.com?Product=HD67E16 www.adfweb.com?Product=HD67E17 www.adfweb.com?Product=HD67E18 www.adfweb.com?Product=HD67E19 www.adfweb.com?Product=HD67E20 www.adfweb.com?Product=HD67E21 www.adfweb.com?Product=HD67E22 www.adfweb.com?Product=HD67E23 www.adfweb.com?Product=HD67E24 www.adfweb.com?Product=HD67E25 www.adfweb.com?Product=HD67E26 www.adfweb.com?Product=HD67E27 www.adfweb.com?Product=HD67E28 www.adfweb.com?Product=HD67879

(Modbus Master) (Modbus Slave) (Modbus TCP Master) (Modbus TCP Slave) (BACnet Master) (BACnet Slave) (CAN) (CANopen) (DeviceNet Master) (DeviceNet Slave) (DMX) (Ethernet) (IEC61850 Client) (IEC61850 Server) (J1939) (MQTT) (NMEA0183) (NMEA2000) (OPC UA Client) (OPC UA Server) (PROFINET Master) (PROFINET Slave) (SNMP Manager) (SNMP Agent) (EtherNet/IP Master) (EtherNet/IP Slave) (S7comm Client) (IO-Link Master)



User Manual



INDEX:

	Page
INDEX	2
UPDATED DOCUMENTATION	2
REVISION LIST	2
WARNING	2
TRADEMARKS	2
SECURITY ALERT	3
EXAMPLE OF CONNECTION	4
CONNECTION SCHEME	5
CHARACTERISTICS	7
CONFIGURATION	7
POWER SUPPLY	8
FUNCTION MODES	9
LEDS	10
ETHERCAT	11
RS232	12
RS485	13
ETHERNET	14
USE OF COMPOSITOR SW67E00	15
NEW CONFIGURATION / OPEN CONFIGURATION	16
SOFTWARE OPTIONS	17
SET COMMUNICATION	19
ETHERCAT SET ACCESS	21
ETHERCAT ESI FILE	23
UPDATE DEVICE	24
SERIAL PROTOCOL	26
MECHANICAL DIMENSIONS	30
ORDERING INFORMATIONS	31
ACCESSORIES	31
DISCLAIMER	32
OTHER REGULATIONS AND STANDARDS	32
WARRANTIES AND TECHNICAL SUPPORT	33
RETURN POLICY	33

User Manual EtherCAT Slave / Serial

Document code: MN67E00 ENG Revision 1.000 Page 2 of 33

UPDATED DOCUMENTATION:

Dear customer, we thank you for your attention and we remind you that you need to check that the following document is:

- → Updated
- → Related to the product you own

To obtain the most recently updated document, note the "document code" that appears at the top right-hand corner of each page of this document.

With this "Document Code" go to web page www.adfweb.com/download/ and search for the corresponding code on the page. Click on the proper "Document Code" and download the updates.

REVISION LIST:

Revision	Date	Author	Chapter	Description
1.000	20/09/2021	Ff	All	First Release

WARNING:

ADFweb.com reserves the right to change information in this manual about our product without warning.

ADFweb.com is not responsible for any error this manual may contain.

TRADEMARKS:

All trademarks mentioned in this document belong to their respective owners.

Document code: MN67E00 ENG Revision 1.000 Page 3 of 33

SECURITY ALERT:

GENERAL INFORMATION

To ensure safe operation, the device must be operated according to the instructions in the manual. When using the device, legal and safety regulation are required for each individual application. The same applies also when using accessories.

INTENDED USE

Machines and systems must be designed so the faulty conditions do not lead to a dangerous situation for the operator (i.e. independent limit switches, mechanical interlocks, etc.).

QUALIFIED PERSONNEL

The device can be used only by qualified personnel, strictly in accordance with the specifications.

Qualified personnel are persons who are familiar with the installation, assembly, commissioning and operation of this equipment and who have appropriate qualifications for their job.

RESIDUAL RISKS

The device is state-of-the-art and is safe. The instruments can represent a potential hazard if they are inappropriately installed and operated by untrained personnel. These instructions refer to residual risks with the following symbol:



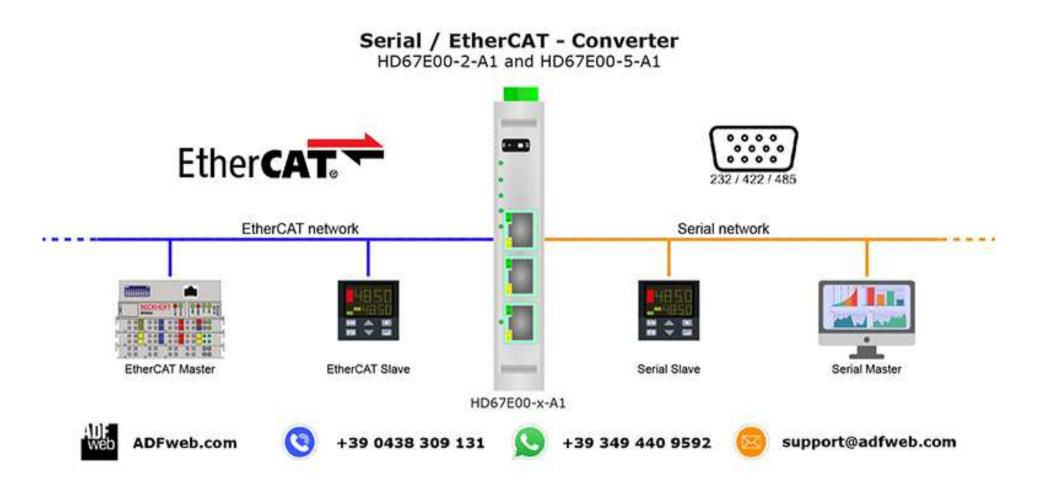
This symbol indicates that non-observance of the safety instructions is a danger for people that could lead to serious injury or death and / or the possibility of damage.

CE CONFORMITY

The declaration is made by our company. You can send an email to support@adfweb.com or give us a call if you need it.

Document code: MN67E00_ENG Revision 1.000 Page 4 of 33

EXAMPLE OF CONNECTION:



Document code: MN67E00_ENG Revision 1.000 Page 5 of 33

CONNECTION SCHEME:

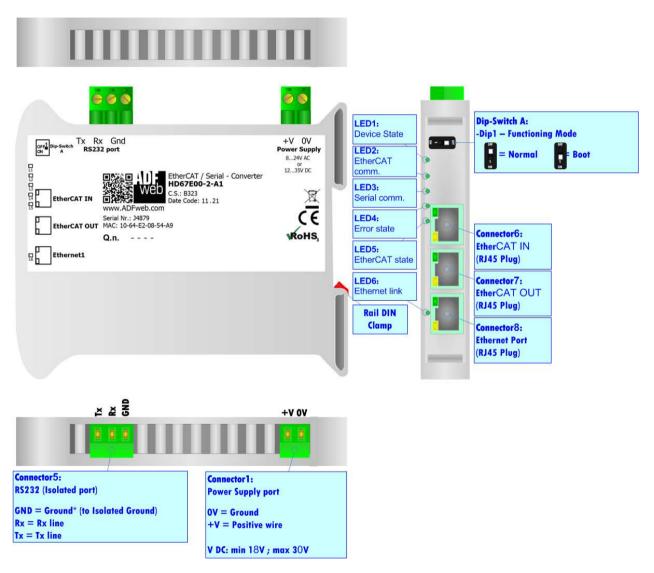


Figure 1a: Connection scheme for HD67E00-2-A1

Document code: MN67E00 ENG Revision 1.000 Page 6 of 33

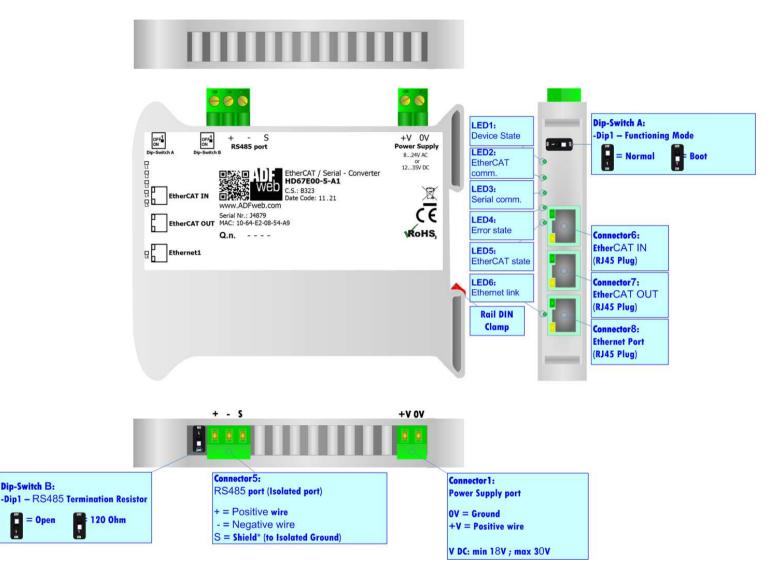


Figure 1b: Connection scheme for HD67E00-5-A1

Dip-Switch B:

Document code: MN67E00_ENG Revision 1.000 Page 7 of 33

CHARACTERISTICS:

The HD67E00-x-A1 are EtherCAT / Serial - Converters.

It allows for the following characteristics:

- → Isolation between EtherCAT Serial Power Supply;
- → Two-directional information between EtherCAT bus and Serial bus;
- → Mountable on 35mm Rail DIN;
- → Wide power supply input range: 8...24V AC or 12...35V DC;
- → Wide temperature range: -40°C / 85°C [-40°F / +185°F].

CONFIGURATION:

You need Compositor SW67E00 software on your PC in order to perform the following:

- Define the parameters of EtherCAT line;
- Define the parameters of Serial line;
- Define EtherCAT variables to read and write;
- Define Modbus registers to read and write from/to the Slaves;;
- Export the ESI file for configuration of EtherCAT Master;
- Update the device.

Document code: MN67E00_ENG Revision 1.000 Page 8 of 33

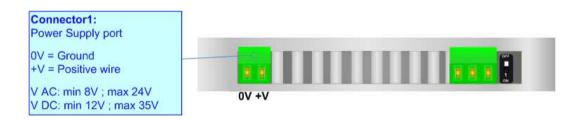
POWER SUPPLY:

The devices can be powered at 8...24V AC and 12...35V DC. For more details see the two tables below.

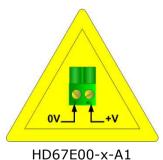
VAC ~		VDC	===
Vmin	Vmax	Vmin	Vmax
8V	24V	12V	35V

Consumption at 24V DC:

Device	Consumption [W/VA]
HD67E00-x-A1	3.5



Caution: Do not reverse the polarity power



Document code: MN67E00_ENG Revision 1.000 Page 9 of 33

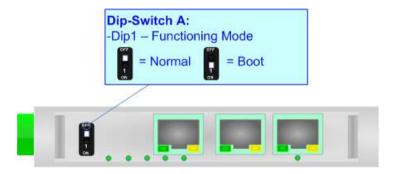
FUNCTION MODES:

The device has got two function modes depending on the position of the 'Dip1 of Dip-Switch A':

- → The first, with 'Dip1 of Dip-Switch A' at "OFF" position, is used for the normal working of the device.
- → The second, with 'Dip1 of Dip-Switch A' at "ON" position, is used for uploading the Project and/or Firmware.

For the operations to follow for the updating, see 'UPDATE DEVICE' section.

According to the functioning mode, the LEDs will have specific functions, see 'LEDS' section.

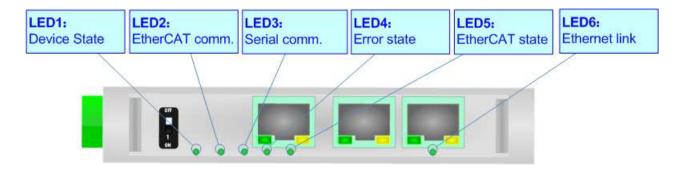


Document code: MN67E00_ENG Revision 1.000 Page 10 of 33

LEDS:

The device has got seven LEDs that are used to give information about the functioning status. The various meanings of the LEDs are described in the table below.

LED	Normal Mode	Boot Mode
1: Device State (green)	Blinks slowly (~1Hz)	Blinks quickly: Boot state Blinks very slowly (~0.5Hz): update in progress
2: EtherCAT comm. (green)	It blinks when EtherCAT communication is running	Blinks quickly: Boot state Blinks very slowly (~0.5Hz): update in progress
3: Serial comm. (green)	It blinks when a Serial request is received	Blinks quickly: Boot state Blinks very slowly (~0.5Hz): update in progress
4: Error state (green)	ON: An error in the communication busses occurs OFF: No errors are present	Blinks quickly: Boot state Blinks very slowly (~0.5Hz): update in progress
5: EtherCAT state (green)	OFF: EtherCAT Master not connected Blinking: EtherCAT Master is connecting ON: EtherCAT Master is connected	Blinks quickly: Boot state Blinks very slowly (~0.5Hz): update in progress
6: Ethernet1 link (green)	ON: Ethernet cable connected OFF: Ethernet cable disconnected	ON: Ethernet cable connected OFF: Ethernet cable disconnected

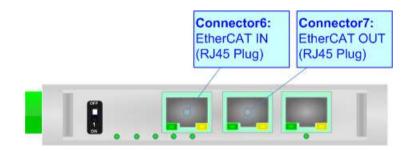


Document code: MN67E00_ENG Revision 1.000 Page 11 of 33

ETHERCAT

EtherCAT (Ethernet for Control Automation Technology) is an Ethernet-based fieldbus system, invented by Beckhoff Automation. The protocol is standardized in IEC 61158 and is suitable for both hard and soft real-time computing requirements in automation technology. With EtherCAT, the standard Ethernet packet or frame (according to IEEE 802.3) is no longer received, interpreted, and copied as process data at every node. The EtherCAT slave devices read the data addressed to them while the telegram passes through the device, processing data "on the fly". In other words, real-time data and messages are prioritized over more general, less time-sensitive or heavy load data.

The converter has two EtherCAT ports, one is used as Input port (Connector6) and it will receive the incoming messages from the Master, the other is used as Output port (Connector7) and i twill forward the messages to the others nodes of the network.

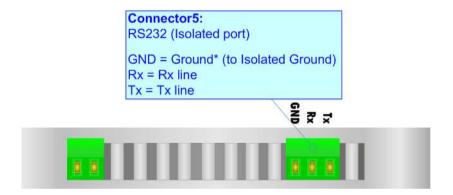


Document code: MN67E00_ENG Revision 1.000 Page 12 of 33

RS232:

The connection from RS232 socket to a serial port (example one from a personal computer) must be made with a NULL MODEM cable (a serial cable where the pins 2 and 3 are crossed).

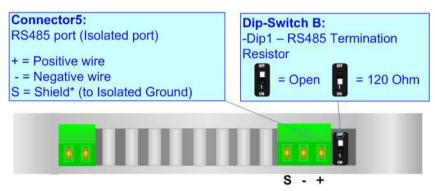
It is recommended that the RS232 cable not exceed 15 meters.



Document code: MN67E00_ENG Revision 1.000 Page 13 of 33

RS485:

For terminate the RS485 line with a 120Ω resistor it is necessary to put ON dip 1, like in figure.



The maximum length of the cable should be 1200m (4000 feet).

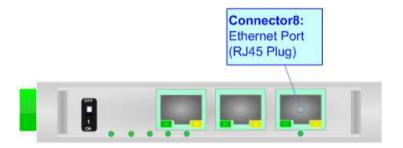
Here some codes of cables:

- → Belden: p/n 8132 2x 28AWG stranded twisted pairs conductor + foil shield + braid shield;
- ▶ Belden p/n 82842 2x 24AWG stranded twisted pairs conductor + foil shield + braid shield;
- ★ Tasker: p/n C521 1x 24AWG twisted pair conductor + foil shield + braid shield;
- ★ Tasker: p/n C522 2x 24AWG twisted pairs conductor + foil shield + braid shield.

Document code: MN67E00_ENG Revision 1.000 Page 14 of 33

ETHERNET:

The updating of the converter must be made using Connector8 of the HD67E00-x-A1 with at least a Category 5E cable. The maximum length of the cable should not exceed 100m. The cable has to conform to the T568 norms relative to connections in cat.5 up to 100 Mbps. To connect the device to an Hub/Switch is recommended the use of a straight cable, to connect the device to a PC/PLC/other is recommended the use of a cross cable.



Document code: MN67E00_ENG Revision 1.000 Page 15 of 33

USE OF COMPOSITOR SW67E00:

To configure the Converter, use the available software that runs with Windows called SW67E00. It is downloadable on the site www.adfweb.com and its operation is described in this document. (This manual is referenced to the last version of the software present on our web site). The software works with MSWindows (XP, Vista, Seven, 8, 10, 11; 32/64bit).

When launching the SW67E00, the window below appears (Fig. 2).



Note:

It is necessary to have installed .Net Framework 4.

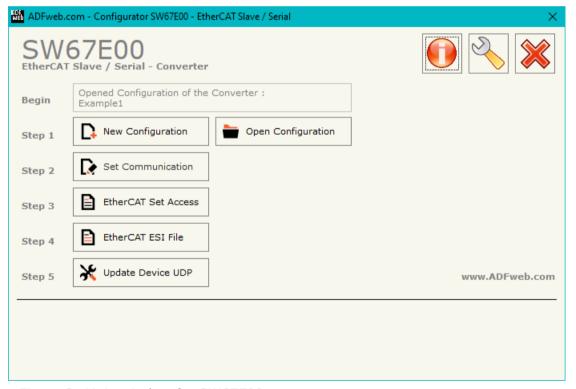


Figure 2: Main window for SW67E00

Document code: MN67E00_ENG Revision 1.000 Page 16 of 33

NEW CONFIGURATION / OPEN CONFIGURATION:

The "New Configuration" button creates the folder which contains the entire device's configuration.



A device's configuration can also be imported or exported:

- → To clone the configurations of a programmable "EtherCAT Slave / Serial Converter" in order to configure another device in the same manner, it is necessary to maintain the folder and all its contents;
- → To clone a project in order to obtain a different version of the project, it is sufficient to duplicate the project folder with another name and open the new folder with the button "Open Configuration".

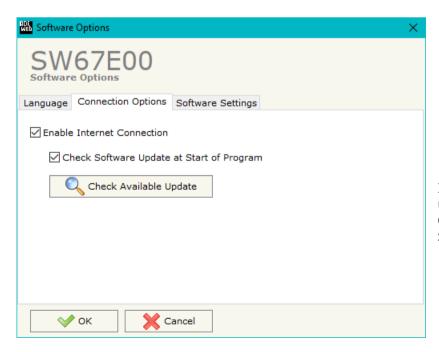


Document code: MN67E00_ENG Revision 1.000 Page 17 of 33

SOFTWARE OPTIONS:

By pressing the "Settings" () button there is the possibility to change the language of the software and check the updatings for the compositor.

In the section "Language" it is possible to change the language of the software.

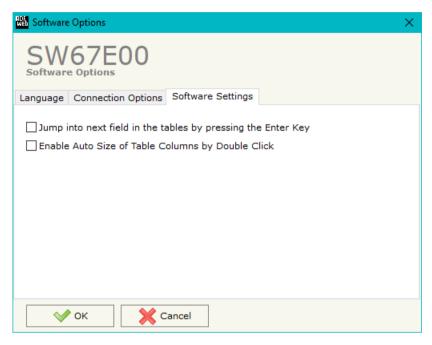




In the section "Connection Options", it is possible to check if there are some updatings of the software compositor in ADFweb.com website. Checking the option "Check Software Update at Start of Program", the SW67E00 checks automatically if there are updatings when it is launched.



Document code: MN67E00_ENG Revision 1.000 Page 18 of 33



In the section "Software Settings", it is possible to enable/disable some keyboard's commands for an easier navigation inside the tables contained in the different sections of the software.

Document code: MN67E00_ENG Revision 1.000 Page 19 of 33

SET COMMUNICATION:

This section define the fundamental communication parameters of two buses, EtherCAT and Serial.

By Pressing the "Set Communication" button from the main window for SW67E00 (Fig. 2) the window "Set Communication" appears (Fig. 3).

The means of the fields for "Ethernet Connection" are:

- → In the field "Device Name (Hostname)" the Hostname to assign to the converter is defined;
- If the field "Obtain an IP Address Automatically (DHCP for Cable Connection)" is checked, DHCP for LAN connection is enabled;
- → If the field "Enable DNS" is checked, DNS protocol is enabled;
- ▶ In the field "Primary DNS" the IP Address of the primary DNS server is defined;
- ▶ In the field "Secondary DNS" the IP Address of the secondary DNS server is defined;
- → If the field "Clear Data on EtherCAT fault" is checked, the data on Serial are set to
 '0' if the EtherCAT communication is in error.

The means of the fields for "EtherCAT Slave" are:

- ▶ In the field "Revision Number" the revision number of the converter is defined;
- ★ In the field "Slave Name" the name of the converter is defined;
- ▶ In the field "Node Address" the ID of the converter is defined.

The means for the fields for the "Serial" are:

- ★ In the field "Serial" the serial port to use is defined (RS232 or RS485);
- In the field "Baudrate" the baudrate for the serial line is defined;
- → In the field "Parity" the parity of the serial line is defined;
- ▶ In the field "Stop Bits" the number of Stop Bits of the serial line is defined

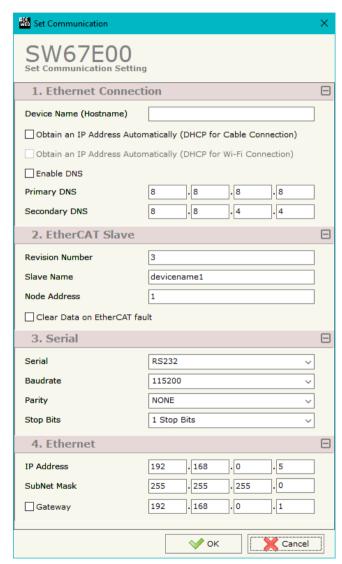


Figure 3: "Set Communication" window



Document code: MN67E00_ENG Revision 1.000 Page 20 of 33

The means of the fields for "Ethernet" are:

- → In the fields "IP Address" the IP address for Ethernet side of the converter is defined;
- → In the fields "SubNet Mask" the SubNet Mask for Ethernet side of the converter is defined;
- ▶ In the fields "Gateway" the default gateway of the net is defined. This feature can be enabled or disabled pressing the Check Box field. This feature is used for going out of the net.

Document code: MN67E00_ENG Revision 1.000 Page 21 of 33

ETHERCAT SET ACCESS:

By Pressing the "EtherCAT Set Access" button from the main window for SW67E00 (Fig. 2) the window "EtherCAT Slave Set Access" appears (Fig. 4).

This section is used to define the EtherCAT variables readable by the EtherCAT Master (Slave To Master) and the EtherCAT variables writeable by the EtherCAT Master (Master To Slave).

SLAVE TO MASTER

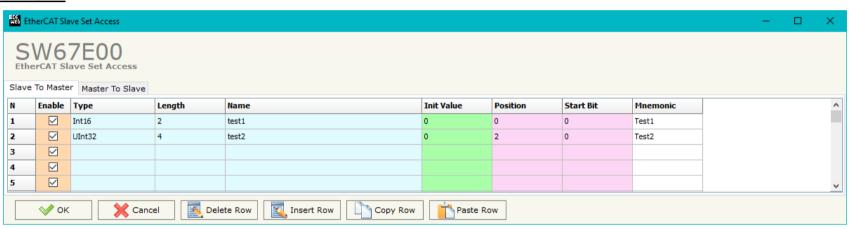


Figure 4a: "EtherCAT Slave Set Access → Slave To Master" window

The means of the fields are:

- ▼ If the field "Enable" is checked, the EtherCAT variable is enabled;
- → In the field "Type" the data format of the EtherCAT variable is defined;
- ▶ In the field "Lenght" the dimension of the EtherCAT variable is defined;
- → In the field "Name" the name of the EtherCAT variable is defined;
- → In the field "Init Value" the default value of the EtherCAT variable is defined;
- ▶ In the field "Position" the starting address of the EtherCAT array where the variable is mapped is defined;
- ▶ In the field "Start Bit" the starting bit of the selected Position where the variable is mapped is defined;
- ▶ In the field "Mnemonic" a description of the variable is defined.

Document code: MN67E00_ENG Revision 1.000 Page 22 of 33

MASTER TO SLAVE



Figure 4b: "EtherCAT Slave Set Access → Master To Slave" window

The means of the fields are:

- → If the field "Enable" is checked, the EtherCAT variable is enabled;
- ▼ In the field "Type" the data format of the EtherCAT variable is defined;
- → In the field "Lenght" the dimension of the EtherCAT variable is defined;
- ▶ In the field "Name" the name of the EtherCAT variable is defined;
- ▶ In the field "Position" the starting address of the EtherCAT array where the variable is mapped is defined;
- ▶ In the field "Start Bit" the starting bit of the selected Position where the variable is mapped is defined;
- ▶ In the field "Mnemonic" a description of the variable is defined.



Document code: MN67E00_ENG Revision 1.000 Page 23 of 33

ETHERCAT ESI FILE:

By pressing the "EtherCAT ESI File" button it is possible to save the ESI file for the EtherCAT side of the converter. The ESI file is used to configure the EtherCAT Master.

Document code: MN67E00_ENG Revision 1.000 Page 24 of 33

UPDATE DEVICE:

By pressing the "**Update Device**" button, it is possible to load the created Configuration into the device; and also the Firmware, if necessary. This by using the Ethernet port.

If you don't know the actual IP address of the device you have to use this procedure:

- → Turn OFF the Device;
- Put Dip1 of 'Dip-Switch A' in ON position;
- Turn ON the device
- Connect the Ethernet cable;
- Insert the IP "192.168.2.205";
- Select which operations you want to do;
- Press the "Execute update firmware" button to start the upload;
- When all the operations are "OK" turn OFF the Device;
- Put Dip1 of 'Dip-Switch A' in OFF position;
- Turn ON the device.

If you know the actual IP address of the device, you have to use this procedure:

- Turn ON the Device with the Ethernet cable inserted;
- Select which operations you want to do;
- Press the "Execute update firmware" button to start the upload;
- ▶ When all the operations are "OK" the device automatically goes at Normal Mode.

At this point the configuration/firmware on the device is correctly updated.



Figure 5: "Update device" windows



Document code: MN67E00_ENG Revision 1.000 Page 25 of 33



Note:

When you receive the device, for the first time, you also have to update the Firmware in the HD67E00 device.

Warning:

If Fig. 6 appears when you try to do the Update try these points before seeking assistance:

- Try to repeat the operations for the updating;
- → Try with another PC;
- Try to restart the PC;
- Check the LAN settings;
- → If you are using the program inside a Virtual Machine, try to use in the main Operating System;
- → If you are using Windows Seven, Vista, 8 or 10 make sure that you have the administrator privileges;
- ▶ In case you have to program more than one device, using the "UDP Update", you have to cancel the ARP table every time you connect a new device on Ethernet. For do this you have to launch the "Command Prompt" and write the command "arp d". Pay attention that with Windows Vista, Seven, 8, 10, 11 you have to launch the "Command Prompt" with Administrator Rights;
- → Pay attention at Firewall lock.



Figure 6: "Error" window



Warning:

In the case of HD67E00 you have to use the software "HD67E00": www.adfweb.com\download\filefold\SW67E00.zip.

Document code: MN67E00_ENG Revision 1.000 Page 26 of 33

SERIAL PROTOCOL:

In order to read and write the data from/to EtherCAT side, it is enough to send some simple commands over serial port.

Reading data from HD67E00 (EtherCAT → Ethernet) by Variable

Request:

Byte Number	Description
1	`E' (0x45)
2	'T' (0x54)
3	'H' (0x48)
4	`E' (0x45)
5	'R' (0x52)
6	'C' (0x43)
7	'A' (0x41)
8	'T' (0x54)
9	'R' (0x52)
10	`.' (0x2E)
11÷13	Index of EtherCAT variable defined in "EtherCAT Access" section (in relation to their definition)

Response:

Byte Number	Description
1	'D' (0x44)
2	`:' (0x3A)
3 ÷ x	Data

Document code: MN67E00_ENG Revision 1.000 Page 27 of 33

Reading data from HD67E00 (EtherCAT → Ethernet) by Array

Request:

Byte Number	Description
1	`E' (0x45)
2	`T' (0x54)
3	'H' (0x48)
4	`E' (0x45)
5	'R' (0x52)
6	'C' (0x43)
7	'A' (0x41)
8	`T' (0x54)
9	'R' (0x52)
10	`.' (0x2E)
11÷13	`FFF' (0x46, 0x46, 0x46)
14	`.' (0x2E)
15÷17	Position (byte) of the EtherCAT array to be read
18	`.' (0x2E)
19÷21	Number of bytes to read

Response:

Byte Number	Description
1	'D' (0x44)
2	`:' (0x3A)
3 ÷ x	Data

Document code: MN67E00_ENG Revision 1.000 Page 28 of 33

Writing data to HD67E00 (Ethernet → EtherCAT) by Variable

Request:

Byte Number	Description
1	`E' (0x45)
2	'T' (0x54)
3	'H' (0x48)
4	'E' (0x45)
5	'R' (0x52)
6	'C' (0x43)
7	'A' (0x41)
8	'T' (0x54)
9	'W' (0x57)
10	`.' (0x2E)
11÷13	Index of EtherCAT variable defined in "EtherCAT
	Access" section (in relation to their definition)
14	`.' (0x2E)
15÷n	Data to write

Response:

Byte Number	Description
1	'D' (0x44)
2	`:' (0x3A)
3 ÷ x	Data written

Document code: MN67E00_ENG Revision 1.000 Page 29 of 33

Writing data to HD67E00 (Ethernet → EtherCAT) by Array

Request:

Byte Number	Description
1	`E' (0x45)
2	'T' (0x54)
3	'H' (0x48)
4	`E' (0x45)
5	'R' (0x52)
6	'C' (0x43)
7	'A' (0x41)
8	'T' (0x54)
9	'R' (0x52)
10	`.' (0x2E)
11÷13	`FFF' (0x46, 0x46, 0x46)
14	`.' (0x2E)
15÷17	Position (byte) of the EtherCAT array to be written
18	`.' (0x2E)
19÷21	Number of bytes to write
22	`.' (0x2E)
23÷25	Data

Response:

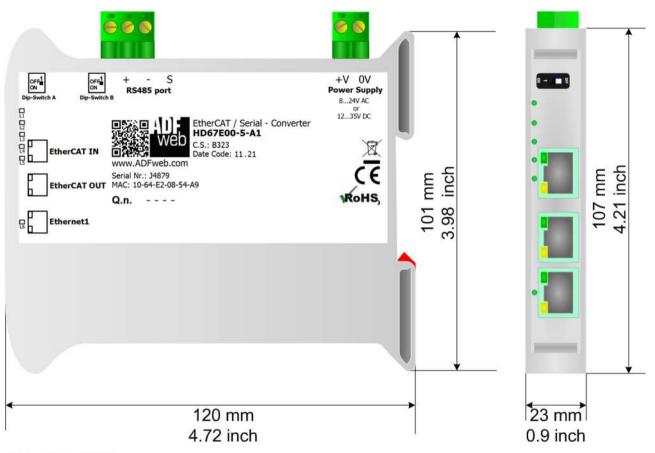
Byte Number	Description
1	'D' (0x44)
2	`:' (0x3A)
3 ÷ x	Data



It is possible to write up to 512 bytes with a single command.

Document code: MN67E00_ENG Revision 1.000 Page 30 of 33

MECHANICAL DIMENSIONS:



Housing: PVC

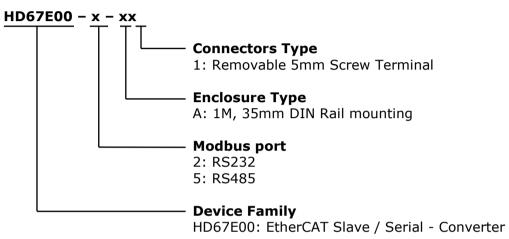
Weight: 200g (Approx)

Figure 7: Mechanical dimensions scheme for HD67E00-x-A1

Document code: MN67E00_ENG Revision 1.000 Page 31 of 33

ORDERING INFORMATIONS:

The ordering part number is formed by a valid combination of the following:



Order Code: **HD67E00-2-A1** - EtherCAT Slave / Serial - Converter (RS232)
Order Code: **HD67E00-5-A1** - EtherCAT Slave / Serial - Converter (RS485)

ACCESSORIES:

Order Code: **AC34011** - 35mm Rail DIN - Power Supply 220/240V AC 50/60Hz - 12 V DC

Order Code: **AC34012** - 35mm Rail DIN - Power Supply 220/240V AC 50/60Hz - 24 V DC

Document code: MN67E00 ENG Revision 1.000 Page 32 of 33

DISCLAIMER:

All technical content within this document can be modified without notice. The content of the document is a under continual renewal. For losses due to fire, earthquake, third party access or other accidents, or intentional or accidental abuse, misuse, or use under abnormal conditions repairs are charged to the user. ADFweb.com S.r.l. will not be liable for accidental loss of use or inability to use this product, such as loss of business income. ADFweb.com S.r.l. shall not be liable for consequences of improper use.

OTHER REGULATIONS AND STANDARDS:

WEEE INFORMATION

Disposal of old electrical and electronic equipment (as in the European Union and other European countries with separate collection systems).

This symbol on the product or on its packaging indicates that this product may not be treated as household rubbish. Instead, it should be taken to an applicable collection point for the recycling of electrical and electronic equipment. If the product is disposed correctly, you will help prevent potential negative environmental factors and impact of human health, which could otherwise be caused by inappropriate disposal. The recycling of materials will help to conserve natural resources. For more information about recycling this product, please contact your local city office, your household waste disposal service or the shop where you purchased the product.

RESTRICTION OF HAZARDOUS SUBSTANCES DIRECTIVE



The device respects the 2002/95/EC Directive on the restriction of the use of certain hazardous substances in electrical **ROHS** and electronic equipment (commonly referred to as Restriction of Hazardous Substances Directive or RoHS).

CE MARKING



The product conforms with the essential requirements of the applicable EC directives.



Document code: MN67E00_ENG Revision 1.000 Page 33 of 33

WARRANTIES AND TECHNICAL SUPPORT:

For fast and easy technical support for your ADFweb.com SRL products, consult our internet support at www.adfweb.com. Otherwise contact us at the address support@adfweb.com

RETURN POLICY:

If while using your product you have any problem and you wish to exchange or repair it, please do the following:

- → Obtain a Product Return Number (PRN) from our internet support at www.adfweb.com. Together with the request, you need to provide detailed information about the problem.
- → Send the product to the address provided with the PRN, having prepaid the shipping costs (shipment costs billed to us will not be accepted).

If the product is within the warranty of twelve months, it will be repaired or exchanged and returned within three weeks. If the product is no longer under warranty, you will receive a repair estimate.



ADFweb.com S.r.I. Via Strada Nuova, 17 IT-31010 Mareno di Piave TREVISO (Italy) Phone +39.0438.30.91.31 Fax +39.0438.49.20.99

www.adfweb.com

