User Manual

Revision 1.000
English

IO-Link Master / EtherCAT Slave - Converter

(Order Code: HD67879-A1-XX)

for Website information:
  www.adfweb.com/?Product=HD67879

for Price information:
  www.adfweb.com/?Price=HD67879-A1-2A
  www.adfweb.com/?Price=HD67879-A1-4A
  www.adfweb.com/?Price=HD67879-A1-2A-2B
  www.adfweb.com/?Price=HD67879-A1-2B
  www.adfweb.com/?Price=HD67879-A1-4B
  www.adfweb.com/?Price=HD67879-A1-4A-4B
  www.adfweb.com/?Price=HD67879-A1-8A

Benefits and Main Features:

  ⊕ Triple electrical isolation
  ⊕ Two Ethernet ports
  ⊕ Temperature range: -40°C/+85°C (-40°F/+185°F)

User Manual

For others IO-Link devices, see also the following links:

IO-Link from/to ...

www.adfweb.com?Product=HD67860	(**Modbus Master**)
www.adfweb.com?Product=HD67861	(**Modbus Slave**)
www.adfweb.com?Product=HD67862	(**Modbus TCP Master**)
www.adfweb.com?Product=HD67864	(**Modbus TCP Slave**)
www.adfweb.com?Product=HD67864	(**BACnet Master**)
www.adfweb.com?Product=HD67865	(**BACnet Slave**)
www.adfweb.com?Product=HD67866	(**CAN**)
www.adfweb.com?Product=HD67867	(**CANopen**)
www.adfweb.com?Product=HD67868	(**DeviceNet Master**)
www.adfweb.com?Product=HD67869	(**DeviceNet Slave**)
www.adfweb.com?Product=HD67870	(**EtherNet/IP Master**)
www.adfweb.com?Product=HD67871	(**EtherNet/IP Slave**)
www.adfweb.com?Product=HD67872	(**J1939**)
www.adfweb.com?Product=HD67873	(**MQTT**)
www.adfweb.com?Product=HD67874	(**NMEA0183**)
www.adfweb.com?Product=HD67875	(**NMEA2000**)
www.adfweb.com?Product=HD67876	(**PROFINET Slave**)
www.adfweb.com?Product=HD67877	(**SNMP Manager**)
www.adfweb.com?Product=HD67878	(**SNMP Agent**)

Do you have an your customer protocol?

See the following links:
www.adfweb.com?Product=HD67879

Do you need to choose a device? do you want help?

Ask it to the following link:
www.adfweb.com?Cmd=helpme

Industrial Electronic Devices

INDEX:

UPDATED DOCUMENTATION:

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- Updated
- Related to the product you own

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With this "Document Code" go to web page www.adfweb.com/download/ and search for the corresponding code on the page. Click on the proper "Document Code" and download the updates.

REVISION LIST:

Revision	Date	Author	Chapter	Description
1.000	14/03/2022	Ff	All	First release version

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Industrial Electronic Devices

SECURITY ALERT:

GENERAL INFORMATION
To ensure safe operation, the device must be operated according to the instructions in the manual. When using the device, legal and safety regulation are required for each individual application. The same applies also when using accessories.

INTENDED USE
Machines and systems must be designed so the faulty conditions do not lead to a dangerous situation for the operator (i.e. independent limit switches, mechanical interlocks, etc.).

QUALIFIED PERSONNEL
The device can be used only by qualified personnel, strictly in accordance with the specifications.
Qualified personnel are persons who are familiar with the installation, assembly, commissioning and operation of this equipment and who have appropriate qualifications for their job.

RESIDUAL RISKS
The device is state-of-the-art and is safe. The instruments can represent a potential hazard if they are inappropriately installed and operated by untrained personnel. These instructions refer to residual risks with the following symbol:

⚠ This symbol indicates that non-observance of the safety instructions is a danger for people that could lead to serious injury or death and / or the possibility of damage.

CE CONFORMITY
The declaration is made by our company. You can send an email to support@adfweb.com or give us a call if you need it.

Industrial Electronic Devices

EXAMPLE OF CONNECTION:

EtherCAT network

IO-Link network

EtherCAT Master

EtherCAT Slave

HD67879-A1

IO-Link Device

IO-Link Device

CONNECTION SCHEME:

Connector13:
IO-Link 2

1 = L+ (device power)
2 = DI (digital input)
3 = L- (device power)
4 = C/Q (IO-Link)

Connector14:
IO-Link 1

1 = L+ (device power)
2 = DI (digital input)
3 = L- (device power)
4 = C/Q (IO-Link)

Dip-Switch A:
-Dip1 – Functioning Mode
= Normal   = Boot

LED1:
Device State

LED2:
EtherCAT comm.

LED3:
IO-Link comm.

LED4:
Error state

LED5:
EtherCAT state

Connector7:
EtherCAT IN
(RJ45 Plug)

Connector8:
EtherCAT OUT
(RJ45 Plug)

LED7:
Ethernet link

Rail DIN Clamp

Connector10:
Ethernet Port
(RJ45 Plug)

Connector1:
Power Supply port

0V = Ground
+V = Positive wire

V DC: min 18V ; max 30V

Figure 1a: Connection scheme for HD67879-A1-2A

Connector11:
IO-Link 4

1 = L+ (device power)
2 = DI (digital input)
3 = L- (device power)
4 = C/Q (IO-Link)

Connector12:
IO-Link 3

1 = L+ (device power)
2 = DI (digital input)
3 = L- (device power)
4 = C/Q (IO-Link)

Connector13:
IO-Link 2

1 = L+ (device power)
2 = DI (digital input)
3 = L- (device power)
4 = C/Q (IO-Link)

Connector14:
IO-Link 1

1 = L+ (device power)
2 = DI (digital input)
3 = L- (device power)
4 = C/Q (IO-Link)

4 3 2 1   4 3 2 1   4 3 2 1   4 3 2 1

Dip-Switch A:
-Dip1 – Functioning Mode
= Normal   = Boot

LED1:
Device State

LED2:
EtherCAT comm.

LED3:
IO-Link comm.

LED4:
Error state

LED5:
EtherCAT state

LED7:
Ethernet link

Rail DIN Clamp

Connector7:
EtherCAT IN
(RJ45 Plug)

Connector8:
EtherCAT OUT
(RJ45 Plug)

Connector10:
Ethernet Port
(RJ45 Plug)

+V 0V
Power Supply
18...30V DC

IO-Link Master / EtherCAT Slave - Converter
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Dip-Switch A

EtherCAT IN

EtherCAT OUT

Ethernet1

IO-Link 4   IO-Link 3   IO-Link 2   IO-Link 1
(Class A)   (Class A)   (Class A)   (Class A)
4 3 2 1   4 3 2 1   4 3 2 1   4 3 2 1

+V 0V

Connector1:
Power Supply port

0V = Ground
+V = Positive wire

V DC: min 18V ; max 30V

Figure 1b: Connection scheme for HD67879-A1-4A

Connector13:
IO-Link 2

1 = L+ (device power)
2 = P24 (output power)
3 = L- (device power)
4 = C/Q (IO-Link)
5 = N24 (output power)

Connector14:
IO-Link 1

1 = L+ (device power)
2 = P24 (output power)
3 = L- (device power)
4 = C/Q (IO-Link)
5 = N24 (output power)

5 4 3 2 1 5 4 3 2 1

Dip-Switch A:
-Dip1 – Functioning Mode

= Normal   = Boot

LED1:
Device State

LED2:
EtherCAT comm.

LED3:
IO-Link comm.

LED4:
Error state

LED5:
EtherCAT state

LED7:
Ethernet link

Rail DIN Clamp

Connector7:
EtherCAT IN
(RJ45 Plug)

Connector8:
EtherCAT OUT
(RJ45 Plug)

Connector10:
Ethernet Port
(RJ45 Plug)

+V 0V   +V 0V
Aux Power Supply   Power Supply
24V DC   18...30V DC

Dip-Switch A

EtherCAT IN

EtherCAT OUT

Ethernet1

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IO-Link 2   IO-Link 1
(Class B)   (Class B)
5 4 3 2 1   5 4 3 2 1

+V 0V

Connector1:
Power Supply port

0V = Ground
+V = Positive wire

V DC: min 18V ; max 30V

Connector2:
Aux Power Supply port
(for IO-Link ports Type B)

0V = Ground
+24V DC = Positive wire

Figure 1c: Connection scheme for HD67879-A1-2B

Connector11:
IO-Link 4

1 = L+ (device power)
2 = DI (digital input)
3 = L- (device power)
4 = C/Q (IO-Link)

Connector12:
IO-Link 3

1 = L+ (device power)
2 = DI (digital input)
3 = L- (device power)
4 = C/Q (IO-Link)

Connector13:
IO-Link 2

1 = L+ (device power)
2 = P24 (output power)
3 = L- (device power)
4 = C/Q (IO-Link)
5 = N24 (output power)

Connector14:
IO-Link 1

1 = L+ (device power)
2 = P24 (output power)
3 = L- (device power)
4 = C/Q (IO-Link)
5 = N24 (output power)

4 3 2 1   4 3 2 1   5 4 3 2 1   5 4 3 2 1

+V 0V   +V 0V
Aux Power Supply Power Supply
24V DC   18...30V DC

Dip-Switch A:
-Dip1 – Functioning Mode

= Normal   = Boot

LED1:
Device State

LED2:
EtherCAT comm.

LED3:
IO-Link comm.

LED4:
Error state

LED5:
EtherCAT state

LED7:
Ethernet link

Connector7:
EtherCAT IN
(RJ45 Plug)

Connector8:
EtherCAT OUT
(RJ45 Plug)

Connector10:
Ethernet Port
(RJ45 Plug)

OFF Dip-Switch ON A

EtherCAT IN

EtherCAT OUT

Ethernet1

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RoHS₂

IO-Link 4   IO-Link 3   IO-Link 2   IO-Link 1
(Class A)   (Class A)   (Class B)   (Class B)
4 3 2 1   4 3 2 1   5 4 3 2 1   5 4 3 2 1

Rail DIN
Clamp

+V 0V

Connector1:
Power Supply port

0V = Ground
+V = Positive wire

V DC: min 18V ; max 30V

Connector2:
Aux Power Supply port
(for IO-Link ports Type B)

0V = Ground
+24V DC = Positive wire

Figure 1d: Connection scheme for HD67879-A1-2A-2B

Connector11:
IO-Link 4

1 = L+ (device power)
2 = P24 (output power)
3 = L- (device power)
4 = C/Q (IO-Link)
5 = N24 (output power)

Connector12:
IO-Link 3

1 = L+ (device power)
2 = P24 (output power)
3 = L- (device power)
4 = C/Q (IO-Link)
5 = N24 (output power)

Connector13:
IO-Link 2

1 = L+ (device power)
2 = P24 (output power)
3 = L- (device power)
4 = C/Q (IO-Link)
5 = N24 (output power)

Connector14:
IO-Link 1

1 = L+ (device power)
2 = P24 (output power)
3 = L- (device power)
4 = C/Q (IO-Link)
5 = N24 (output power)

5 4 3 2 1   5 4 3 2 1   5 4 3 2 1   5 4 3 2 1

Dip-Switch A:
-Dip1 – Functioning Mode

= Normal   = Boot

LED1:
Device State

LED2:
EtherCAT comm.

LED3:
IO-Link comm.

LED4:
Error state

LED5:
EtherCAT state

LED7:
Ethernet link

Rail DIN Clamp

Connector7:
EtherCAT IN
(RJ45 Plug)

Connector8:
EtherCAT OUT
(RJ45 Plug)

Connector10:
Ethernet Port
(RJ45 Plug)

OFF Dip-Switch
ON   A

EtherCAT IN

EtherCAT OUT

Ethernet1

+V 0V   +V 0V
Aux Power Supply Power Supply
24V DC   18...30V DC

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RoHS

IO-Link 4   IO-Link 3   IO-Link 2   IO-Link 1
(Class B)   (Class B)   (Class B)   (Class B)
5 4 3 2 1   5 4 3 2 1   5 4 3 2 1   5 4 3 2 1

+V 0V +V 0V

Connector1:
Power Supply port

0V = Ground
+V = Positive wire

V DC: min 18V ; max 30V

Connector2:
Aux Power Supply port
(for IO-Link ports Type B)

0V = Ground
+24V DC = Positive wire

Figure 1e: Connection scheme for HD67879-A1-4B

Connector11:
IO-Link 4

1 = L+ (device power)
2 = P24 (output power)
3 = L- (device power)
4 = C/Q (IO-Link)
5 = N24 (output power)

Connector12:
IO-Link 3

1 = L+ (device power)
2 = P24 (output power)
3 = L- (device power)
4 = C/Q (IO-Link)
5 = N24 (output power)

Connector13:
IO-Link 2

1 = L+ (device power)
2 = P24 (output power)
3 = L- (device power)
4 = C/Q (IO-Link)
5 = N24 (output power)

Connector14:
IO-Link 1

1 = L+ (device power)
2 = P24 (output power)
3 = L- (device power)
4 = C/Q (IO-Link)
5 = N24 (output power)

LED1:
Device State

LED2:
EtherCAT comm.

LED3:
IO-Link comm.

LED4:
Error state

LED5:
EtherCAT state

LED7:
Ethernet link

Rail DIN Clamp

Dip-Switch A:
-Dip1 – Functioning Mode

= Normal   = Boot

Connector7:
EtherCAT IN
(RJ45 Plug)

Connector8:
EtherCAT OUT
(RJ45 Plug)

Connector10:
Ethernet Port
(RJ45 Plug)

Connector6:
IO-Link 5

1 = L+ (device power)
2 = DI (digital input)
3 = L- (device power)
4 = C/Q (IO-Link)

Connector5:
IO-Link 6

1 = L+ (device power)
2 = DI (digital input)
3 = L- (device power)
4 = C/Q (IO-Link)

Connector4:
IO-Link 7

1 = L+ (device power)
2 = DI (digital input)
3 = L- (device power)
4 = C/Q (IO-Link)

Connector3:
IO-Link 8

1 = L+ (device power)
2 = DI (digital input)
3 = L- (device power)
4 = C/Q (IO-Link)

Connector1:
Power Supply port

0V = Ground
+V = Positive wire

V DC: min 18V ; max 30V

Connector2:
Aux Power Supply port
(for IO-Link ports Type B)

0V = Ground
+24V DC = Positive wire

Figure 1f: Connection scheme for HD67879-A1-4A-4B

Connector11:
IO-Link 4

1 = L+ (device power)
2 = DI (digital input)
3 = L- (device power)
4 = C/Q (IO-Link)

Connector12:
IO-Link 3

1 = L+ (device power)
2 = DI (digital input)
3 = L- (device power)
4 = C/Q (IO-Link)

Connector13:
IO-Link 2

1 = L+ (device power)
2 = DI (digital input)
3 = L- (device power)
4 = C/Q (IO-Link)

Connector14:
IO-Link 1

1 = L+ (device power)
2 = DI (digital input)
3 = L- (device power)
4 = C/Q (IO-Link)

4 3 2 1   4 3 2 1   4 3 2 1   4 3 2 1

Dip-Switch A:
-Dip1 – Functioning Mode

= Normal   = Boot

1 2 3 4 1 2 3 4 1 2 3 4 1 2 3 4
IO-Link 5 IO-Link 6 IO-Link 7 IO-Link 8
(Class A) (Class A) (Class A) (Class A)

+V 0V
Power Supply
18...30V DC

OFF Dip-Switch
ON A

EtherCAT IN

EtherCAT OUT

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Ethernet1

IO-Link 4   IO-Link 3   IO-Link 2   IO-Link 1
(Class A)   (Class A)   (Class A)   (Class A)
4 3 2 1   4 3 2 1   4 3 2 1   4 3 2 1

LED1:
Device State

LED2:
EtherCAT
comm.

LED3:
IO-Link comm.

LED4:
Error state

LED5:
EtherCAT state

LED7:
Ethernet link

Rail DIN
Clamp

Connector7:
EtherCAT IN
(RJ45 Plug)

Connector8:
EtherCAT OUT
(RJ45 Plug)

Connector10:
Ethernet Port
(RJ45 Plug)

Connector1:
Power Supply port

0V = Ground
+V = Positive wire

V DC: min 18V ; max 30V

1 2 3 4 1 2 3 4 1 2 3 4 1 2 3 4   +V 0V

Connector6:
IO-Link 5

1 = L+ (device power)
2 = DI (digital input)
3 = L- (device power)
4 = C/Q (IO-Link)

Connector5:
IO-Link 6

1 = L+ (device power)
2 = DI (digital input)
3 = L- (device power)
4 = C/Q (IO-Link)

Connector4:
IO-Link 7

1 = L+ (device power)
2 = DI (digital input)
3 = L- (device power)
4 = C/Q (IO-Link)

Connector3:
IO-Link 8

1 = L+ (device power)
2 = DI (digital input)
3 = L- (device power)
4 = C/Q (IO-Link)

Figure 1g: Connection scheme for HD67879-A1-8A

CHARACTERISTICS:

The HD67879-A1 is a IO-Link Master / EtherCAT Slave converter.

It allows the following characteristics:

- Up to 1499 bytes in reading and 1499 bytes in writing;
- Two-directional information between EtherCAT and IO-Link;
- Mountable on 35mm Rail DIN;
- Wide power supply input range: 18…30V DC;
- Wide temperature range: -40°C / 85°C [-40°F / +185°F].

CONFIGURATION:

You need Compositor SW67879 software on your PC in order to perform the following:

- Define the parameters of IO-Link;
- Define the parameters of EtherCAT;
- Define IO-Link variables to be read by EtherCAT Master;
- Define IO-Link variables to be written by EtherCAT Master;
- Define EtherCAT variables to read and write;
- Export the ESI file for configuration of EtherCAT Master;
- Update the device.

POWER SUPPLY:

The devices can be powered between a wide range of tensions. For more details see the two tables below.

	VDC	
	Vmin	**Vmax**
HD67879-A1-xx	**18V**	**30V**

Consumption at 24V DC:

Device	**W/VA**
HD67879-A1-xx	4

⚠ Warning:
    It is necessary to add to this consumption the one required by the IO-Link devices connected to the IO-Link channels.

⚠ **Caution: Not reverse the polarity power**
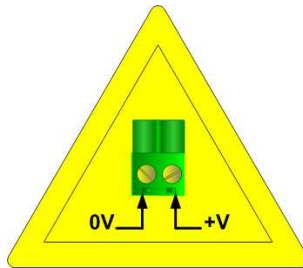
HD67879-A1-xx

Connector1:
Power Supply port

0V = Ground
+V = Positive wire

V DC: min 18V ; max 30V

0V +V

Connector1:
Power Supply port

0V = Ground
+V = Positive wire

V DC: min 18V ; max 30V

0V +V
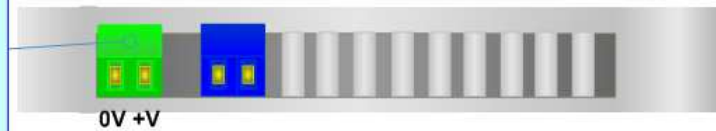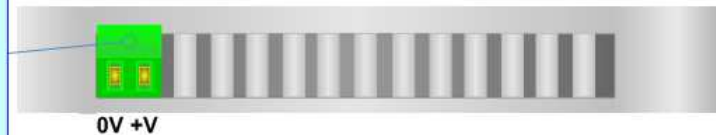
FUNCTION MODES:

The device has got two functions mode depending of the position of the Dip1 of 'Dip-Switch A':

◈ The first, with Dip1 in Off position (factory setting), is used for the normal working of the device.

◈ The second, with Dip1 in On position, is used for upload the Project/Firmware.

For the operations to follow for the updating (see 'UPDATE DEVICE' section).

According to the functioning mode, the LEDs will have specifics functions (see 'LEDS' section).
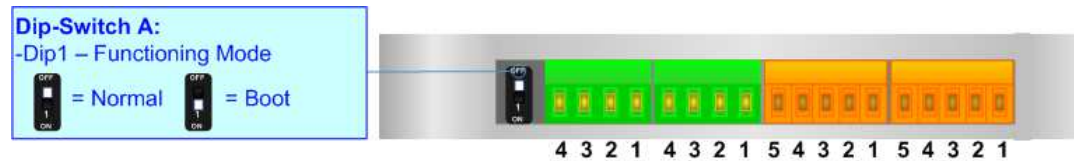
LEDS:

The device has got five LEDs that are used to give information of the functioning status.
The various meanings of the LEDs are described in the table below.

LED	Normal Mode	Boot Mode
1: Device State (green)	Blinks slowly (~1Hz)	**Blinks quickly:** Boot state **Blinks very slowly (~0.5Hz):** update in progress
2: EtherCAT comm. (green)	It blinks when EtherCAT communication is running	**Blinks quickly:** Boot state **Blinks very slowly (~0.5Hz):** update in progress
3: IO-Link comm. (green)	It blinks when IO-Link communication is running	**Blinks quickly:** Boot state **Blinks very slowly (~0.5Hz):** update in progress
4: Error state (green)	**ON:** An error in the communication busses occurs **OFF:** No errors are present	**Blinks quickly:** Boot state **Blinks very slowly (~0.5Hz):** update in progress
5: EtherCAT state (green)	**OFF:** EtherCAT Master not connected **Blinking:** EtherCAT Master is connecting **ON:** EtherCAT Master is connected	**Blinks quickly:** Boot state **Blinks very slowly (~0.5Hz):** update in progress
7: Ethernet2 link (green)	**ON:** Ethernet cable connected **OFF:** Ethernet cable disconnected	**ON:** Ethernet cable connected **OFF:** Ethernet cable disconnected
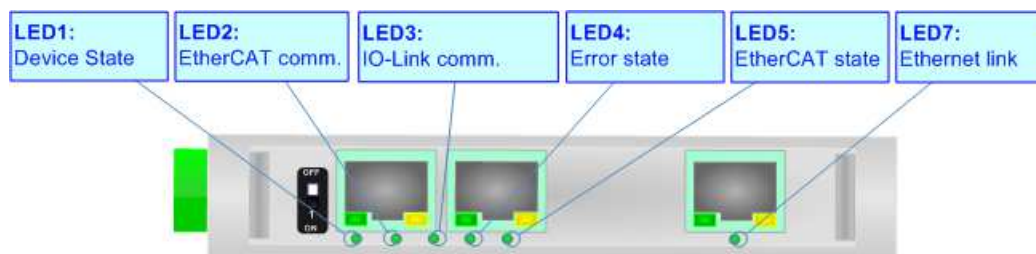
IO-LINK

IO-Link is the first globally standardized IO technology (IEC 61131-9) that communicates from the controller down to the lowest automation level. This universally applicable interface is a fieldbus-neutral point-to-point connection which uses standard unshielded cables. IO-Link sends all the sensor and actuator signals to the controller and in turn carries controller data to the sensor/actuator level with revolutionary consequences.
It is possible to have IO-Link device of two different type: IO-Link Class A and IO-Link Class B. ADFweb.com's converters can manage both of them in relation to the product code selected.

IO-LINK CLASS A:

IO-Link Class A devices uses 4 pins on connectors and the input power required can be up to 200mA. These devices are normally sensors and actuators that don't require high input power.

Connector11:
IO-Link 4

1 = L+ (device power)
2 = DI (digital input)
3 = L- (device power)
4 = C/Q (IO-Link)

Connector12:
IO-Link 3

1 = L+ (device power)
2 = DI (digital input)
3 = L- (device power)
4 = C/Q (IO-Link)

Connector13:
IO-Link 2

1 = L+ (device power)
2 = DI (digital input)
3 = L- (device power)
4 = C/Q (IO-Link)

Connector14:
IO-Link 1

1 = L+ (device power)
2 = DI (digital input)
3 = L- (device power)
4 = C/Q (IO-Link)

4 3 2 1   4 3 2 1   4 3 2 1   4 3 2 1
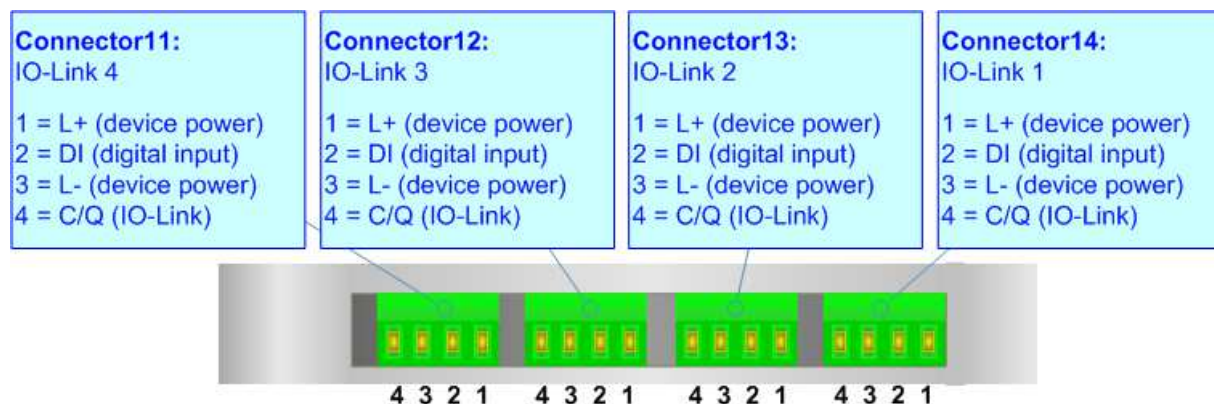
IO-LINK CLASS B:

IO-Link Class B devices uses 5 pins on connectors and they require an additional aux power supply used for the actuation. These devices are normally actuators.
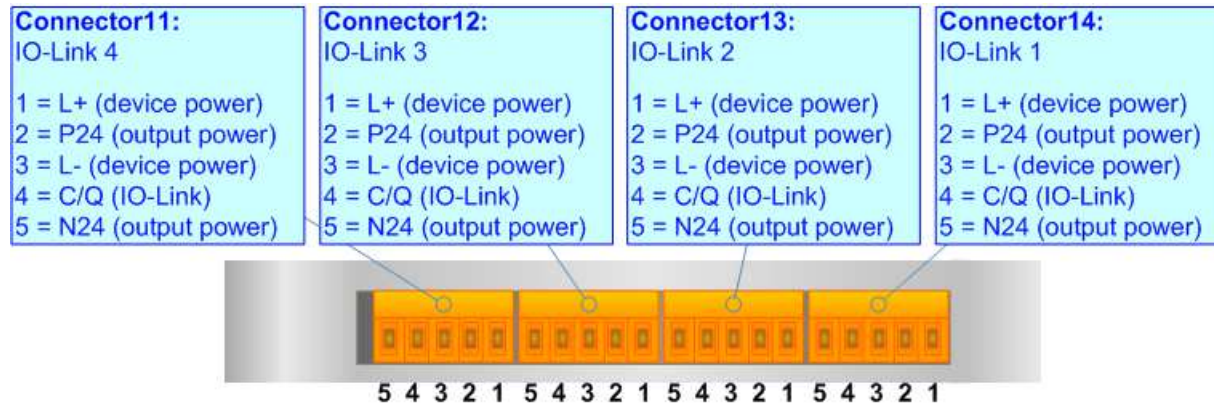
AUX POWER SUPPLY (for IO-Link Class B):

The Aux Power Supply port is used to provide the additional power supply for the IO-Link Class B. The input voltage is fixed to 24 V DC and the current depends on the input power required by the IO-Link devices connected to the IO-Link channels Class B.
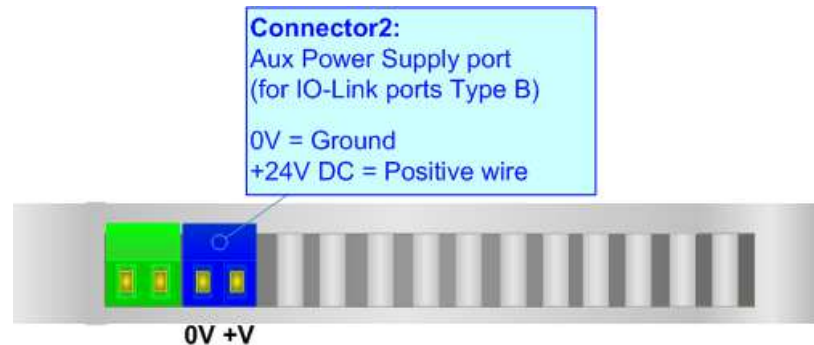
ETHERCAT

EtherCAT (Ethernet for Control Automation Technology) is an Ethernet-based fieldbus system, invented by Beckhoff Automation.

The protocol is standardized in IEC 61158 and is suitable for both hard and soft real-time computing requirements in automation technology.

With EtherCAT, the standard Ethernet packet or frame (according to IEEE 802.3) is no longer received, interpreted, and copied as process data at every node. The EtherCAT slave devices read the data addressed to them while the telegram passes through the device, processing data "on the fly". In other words, real-time data and messages are prioritized over more general, less time-sensitive or heavy load data.

The converter has two EtherCAT ports, one is used as Input port (Connector7) and it will receive the incoming messages from the Master, the other is used as Output port (Connector8) and i twill forward the messages to the others nodes of the network.
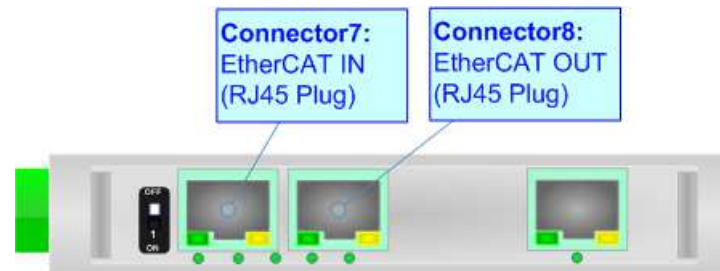
ETHERNET:

The Ethernet connection must be made using Connector10 of HD67879-A1 with at least a Category 5E cable. The maximum length of the cable should not exceed 100m. The cable has to conform to the T568 norms relative to connections in cat.5 up to 100 Mbps. To connect the device to an Hub/Switch is recommended the use of a straight cable, to connect the device to a PC/PLC/other is recommended the use of a cross cable.
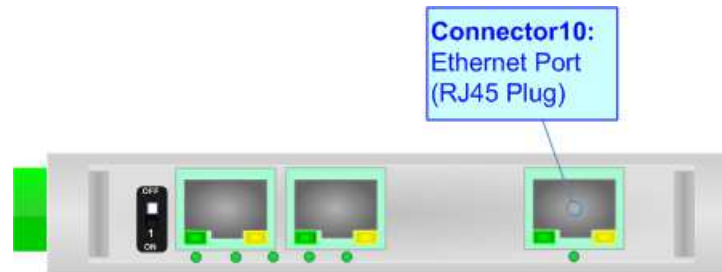
USE OF COMPOSITOR SW67879:

To configure the Converter, use the available software that runs with Windows called SW67879. It is downloadable on the site www.adfweb.com and its operation is described in this document. *(This manual is referenced to the last version of the software present on our web site)*. The software works with MSWindows (XP, Vista, Seven, 8, 10, 11; 32/64bit).

When launching the SW67879, the window below appears (Fig. 2).

Note:
It is necessary to have installed .Net Framework 4.
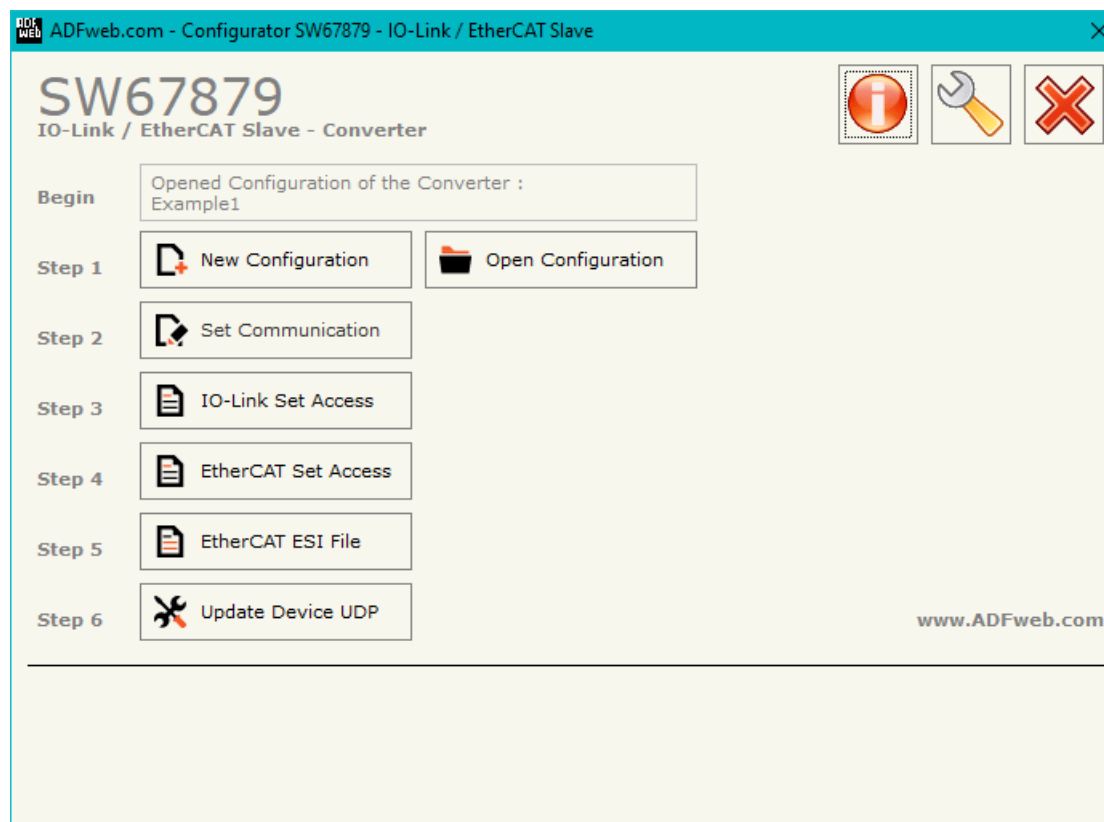
Figure 2: Main window for SW67879

NEW CONFIGURATION / OPEN CONFIGURATION:

The "**New Configuration**" button creates the folder which contains the entire device's configuration.
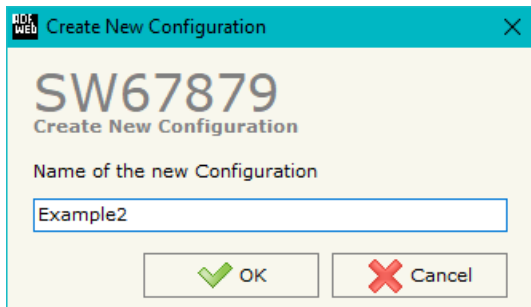
A device's configuration can also be imported or exported:

- To clone the configurations of a programmable "IO-Link Master / EtherCAT Slave - Converter" in order to configure another device in the same manner, it is necessary to maintain the folder and all its contents;
- To clone a project in order to obtain a different version of the project, it is sufficient to duplicate the project folder with another name and open the new folder with the button "**Open Configuration**".

Industrial Electronic Devices
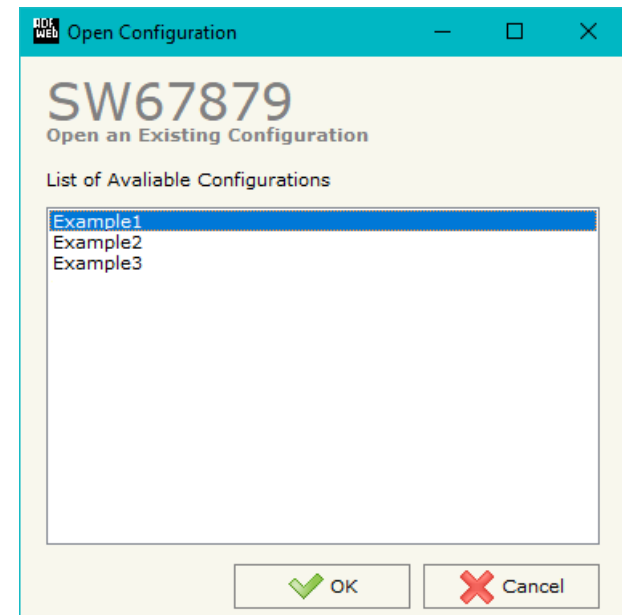
SOFTWARE OPTIONS:

By pressing the "**Settings**" (🔧) button there is the possibility to change the language of the software and check the updatings for the compositor.

In the section "Language" it is possible to change the language of the software.
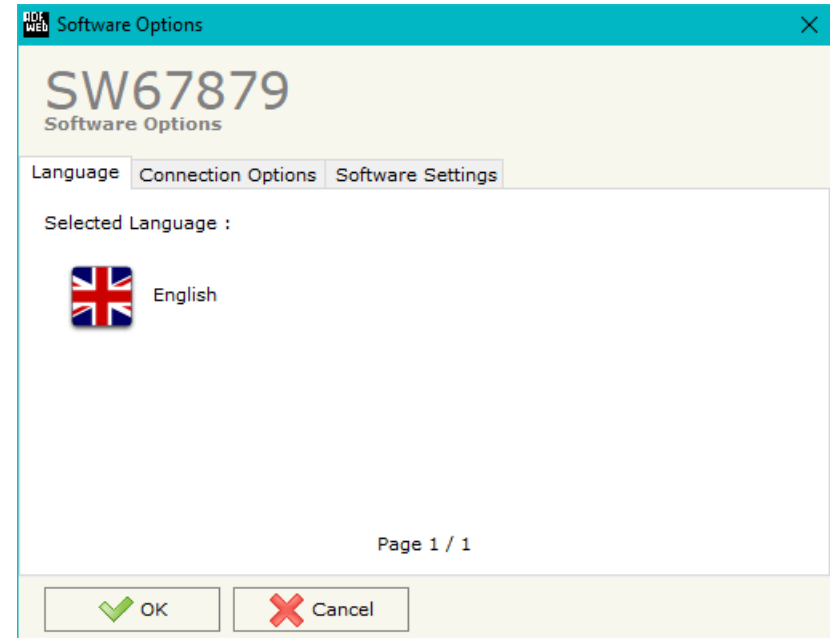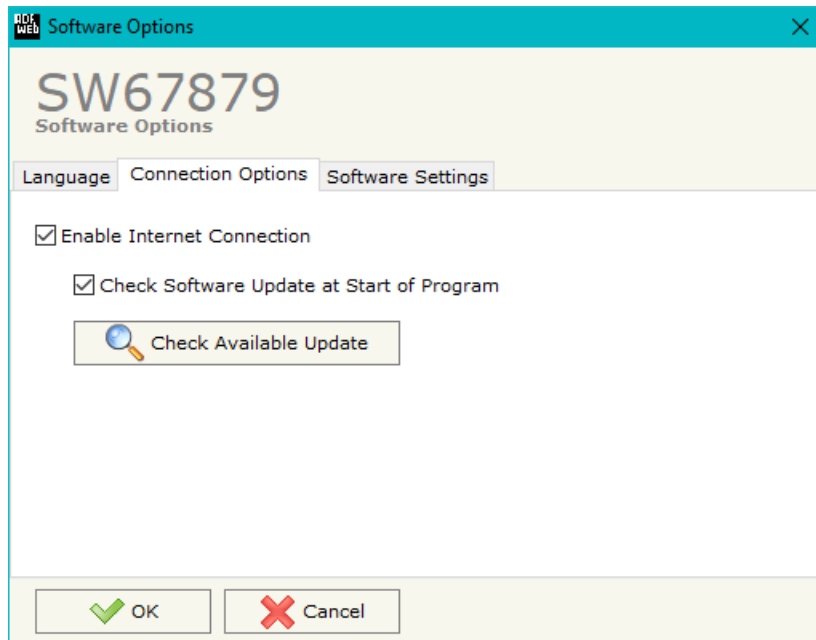
In the section "Connection Options", it is possible to check if there are some updatings of the software compositor in ADFweb.com website.
Checking the option "**Check Software Update at Start of Program**", the SW67879 check automatically if there are updatings when it is launched.
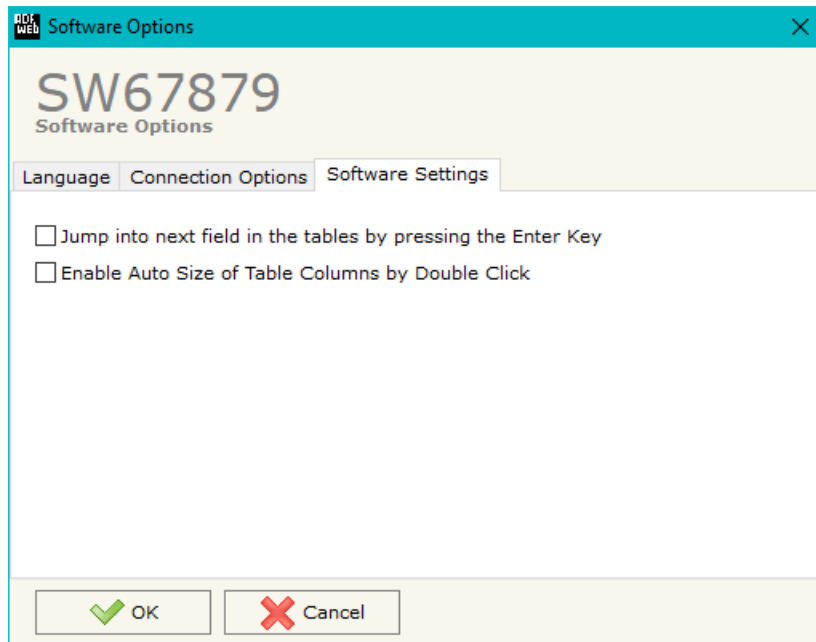
In the section "Software Settings", it is possible to enable/disable some keyboard's commands for an easier navigation inside the tables contained in the different sections of the software.

Software Options

SW67879
Software Options

Language | Connection Options | Software Settings

☐ Jump into next field in the tables by pressing the Enter Key
☐ Enable Auto Size of Table Columns by Double Click

✔ OK   ✖ Cancel

SET COMMUNICATION:

This section define the fundamental communication parameters of two buses, EtherCAT and Modbus TCP.

By Pressing the "**Set Communication**" button from the main window for SW67E04 (Fig. 2) the window "Set Communication" appears (Fig. 3).

The means of the fields for "Ethernet Connection" are:
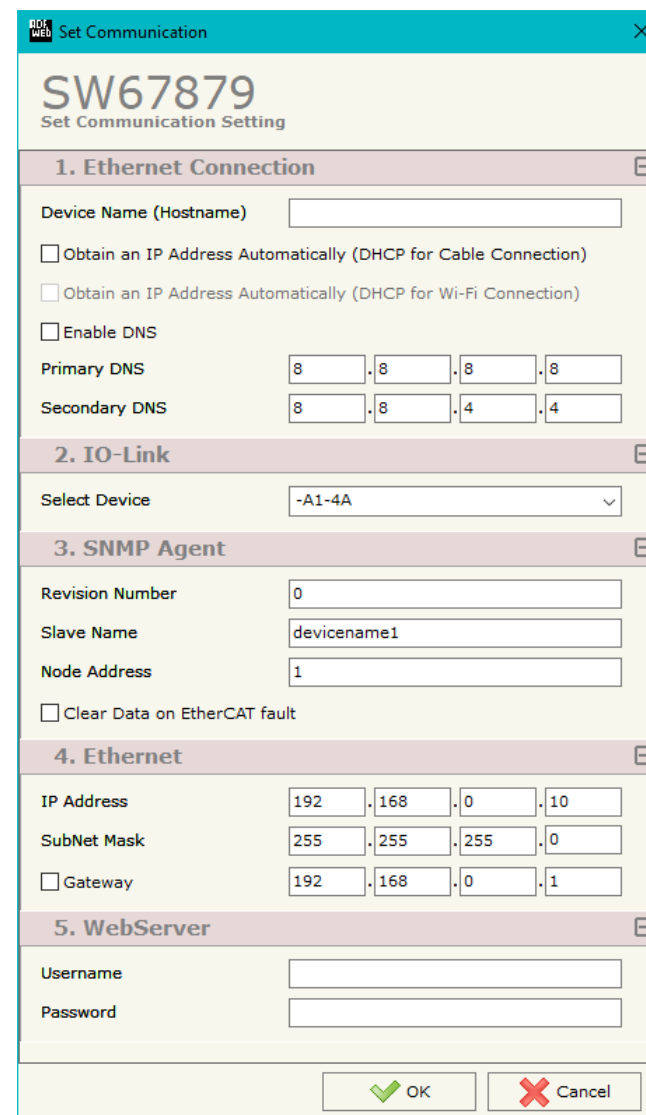
- In the field "**Device Name (Hostname)**" the Hostname to assign to the converter is defined;
- If the field "**Obtain an IP Address Automatically (DHCP for Cable Connection)**" is checked, DHCP for LAN connection is enabled;
- If the field "**Enable DNS**" is checked, DNS protocol is enabled;
- In the field "**Primary DNS**" the IP Address of the primary DNS server is defined;
- In the field "**Secondary DNS**" the IP Address of the secondary DNS server is defined.

The means of the fields for "IO-Link" are:

- In the field "**Select Device**" the type of IO-LINK channels is defined.

The means of the fields for "EtherCAT Slave" are:

- In the field "**Revision Number**" the revision number of the converter is defined;
- In the field "**Slave Name**" the name of the converter is defined;
- In the field "**Node Address**" the ID of the converter is defined.

Figure 3a: "Set Communication" window

The means of the fields for "Ethernet" are:

- In the field "**IP Address**" the IP address of the converter is defined;
- In the field "**Subnet Mask**" the SubNet Mask of the converter is defined;
- In the field "**GATEWAY**" the default gateway of the net is defined. This feature can be enabled or disabled pressing the Check Box field. This feature is used for going out of the net;

The means of the fields for "Webserver" are:

- In the field "**Username**" the username for accessing to the webserver of the converter is defined;
- In the field "**Password**" the password for accessing to the webserver of the converter is defined;

IO-LINK SET ACCESS:

By Pressing the "**IO-Link Set Access**" button from the main window for SW67879 (Fig. 2) the window "IO-Link Set Access" appears (Fig. 4).
This section is used to define the list of IO-Link variables accessible from EtherCAT side.
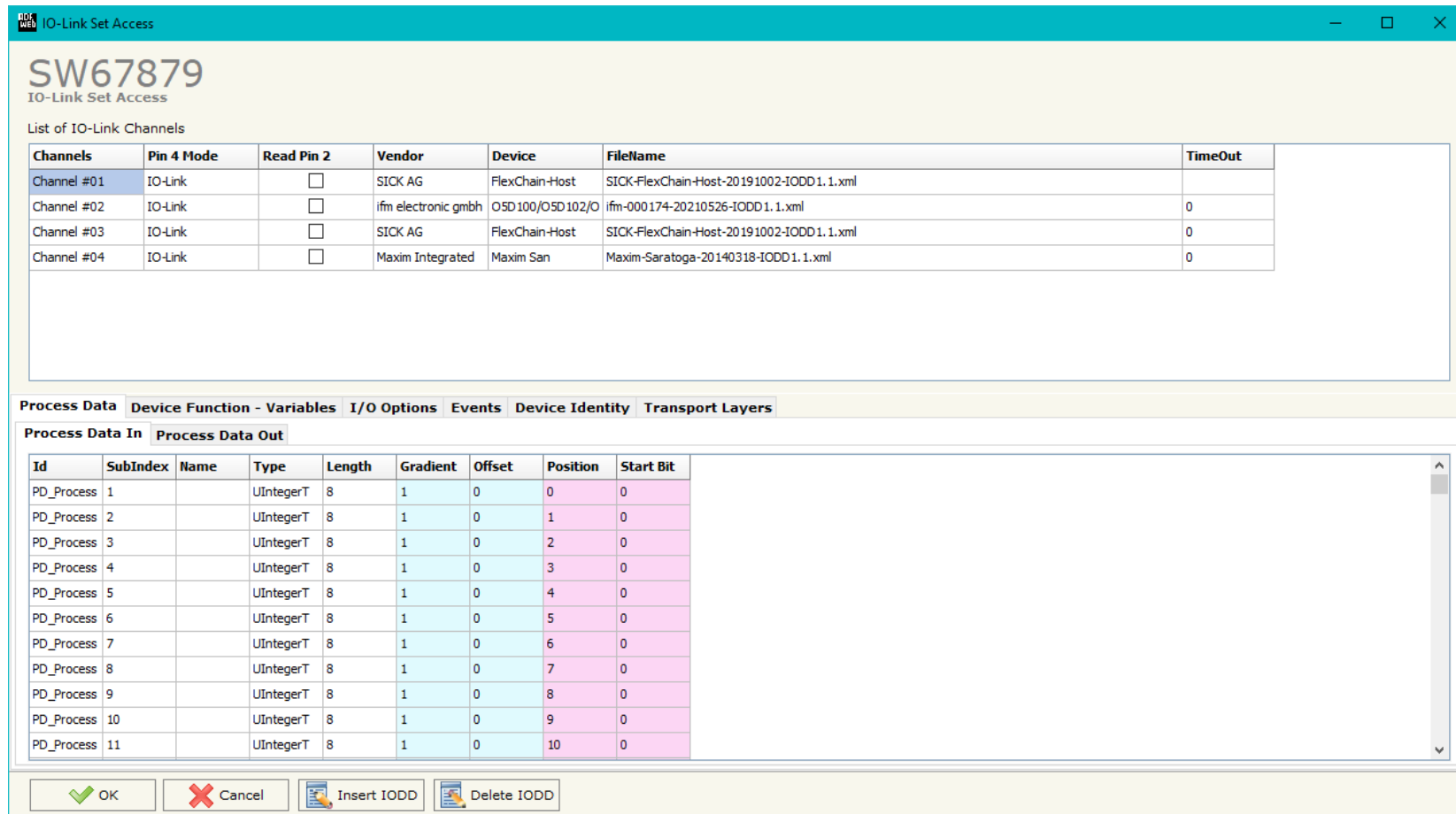
Figure 4: "IO-Link Set Access" window

In the "List of IO-Link Channel" section it is possible to configure all the IO-Link channels of the converter (Fig. 5).

List of IO-Link Channels

Channels	Pin 4 Mode	Read Pin 2	Vendor	Device	FileName
Channel #01	IO-Link	☐	ifm electronic gmbh	O5D100/O5D102/O	ifm-000174-20150804-IODD1.1.xml
Channel #02	IO-Link	☐	ifm electronic gmbh	ROP520 / ROP521	ifm-0001F0-20170324-IODD1.1.xml
Channel #03	IO-Link	☐	Maxim Integrated	Maxim Servo	Maxim-ServoInterface-20150131-IODD1.1.xml
Channel #04	IO-Link	☐	ifm electronic gmbh	TA2**5	ifm-000179-20160325-IODD1.1.xml

Figure 5: "List of IO-Link Channel" section

The meanings of the fields are:

- In the field "**Channels**" the index of the IO-Link channel is defined;
- In the field "**Pin 4 Mode**" the mode of the pin 4 of the IO-Link device is defined (if "Io-Link" is selected, a file IODD is needed);
- If the field "**Read Pin 2**" is checked, the pin 2 of the IO-Link device is read;
- In the field "**Vendor**" the vendor of the IO-Link device is defined;
- In the field "**Device**" the name of the IO-Link device is defined;
- In the field "**FileName**" the name of the IODD file inserted is defined;
- In the field "**Timeout**" the timeout for IO-Link communication is defined. If there is no communication for the defined timeout, the data on EtherCAT will be set to 0.

Industrial Electronic Devices

By clicking on "**Insert IODD**", the window "IO-Link IODD Catalog" appears (Fig. 6). This section is used to select an IO-Link device. By clicking on "**Add IODD**" it is possible to add a new IODD file (the extension must be .xml).
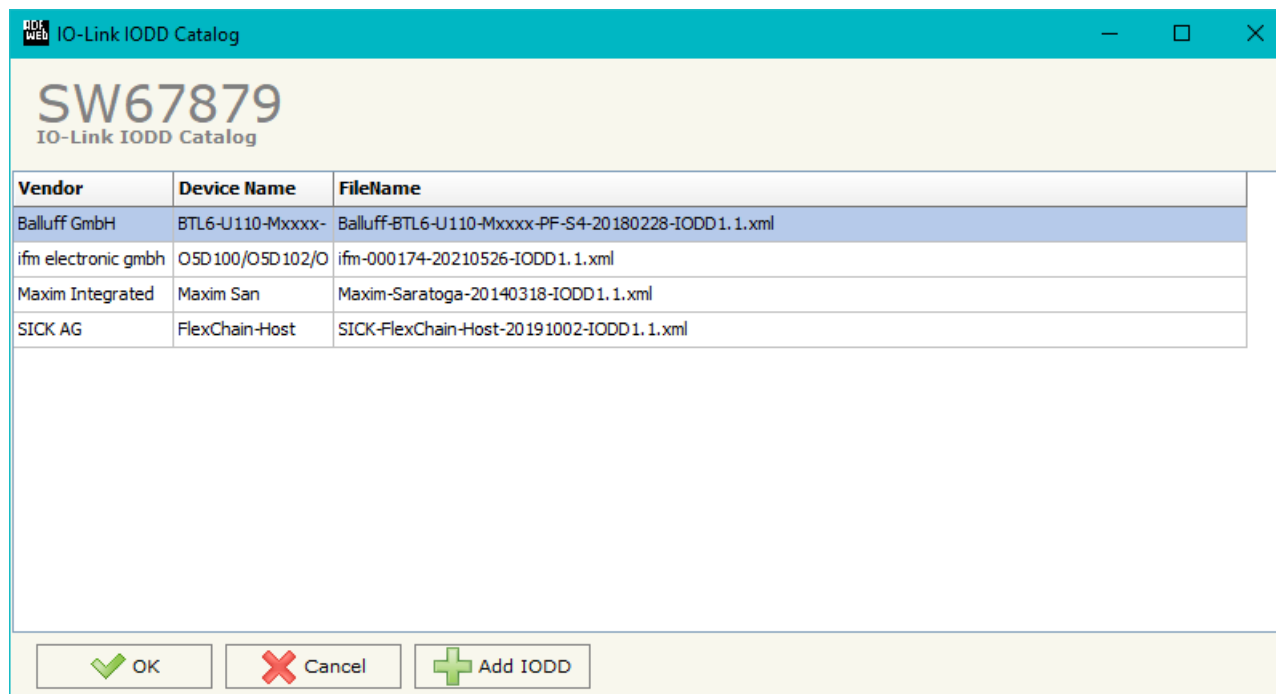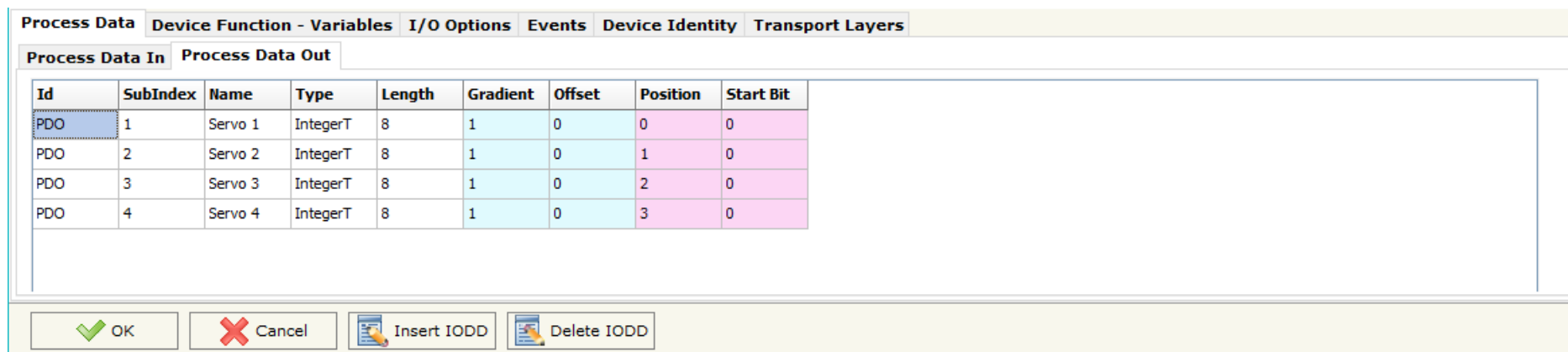
Figure 6: "IO-Link IODD Catalog" section

The "Process Data" section is used to define the IO-Link process data to link to EtherCAT side (Fig. 7).

Id	SubIndex	Name	Type	Length	Gradient	Offset	Position	Start Bit
PDO	1	Servo 1	IntegerT	8	1	0	0	0
PDO	2	Servo 2	IntegerT	8	1	0	1	0
PDO	3	Servo 3	IntegerT	8	1	0	2	0
PDO	4	Servo 4	IntegerT	8	1	0	3	0

Figure 7: "Process Data" section

The meanings of the fields are:

➢ In the field "**Id**" the Id of the IO-Link process data is defined;
➢ In the field "**SubIndex**" the subindex of the IO-Link process data is defined;
➢ In the field "**Name**" the name of the IO-Link process data is defined;
➢ In the field "**Type**" the data format of the IO-Link process data is defined;
➢ In the field "**Length**" the bit length of the IO-Link process data is defined;
➢ In the field "**Gradient**" the multiplication factor of the IO-Link process data is defined;
➢ In the field "**Offset**" the offset of the IO-Link process data is defined;
➢ In the field "**Position**" the starting byte of the internal memory arrays where mapping/getting the value is defined;
➢ In the field "**Start Bit**" the starting bit of the byte of the field "Position" is defined.

The "Device Function – Variables" section is used to define the IO-Link parameters to link to EtherCAT side (Fig. 8).

Enable	Index	SubIndex	Id	Name	Type	Access	Length	SindAccSupp	TotBitLen	BitOff	Default	Value	Description
☐	542		V_Operating_Hours	Operating_Hours	UIntegerT	Read Only	16	False	16	0			Operating hours
☐	551		V_uni	uni	UIntegerT	Read Write	8	False	8	0	0		Selection of unit on
☐	552		V_diS	diS	RecordT	Read Write	16	False	16	0			Display settings
☐	552	1	V_diS	Display On / OFF	BooleanT	Read Write	1	False	16	7	false		
☐	552	2	V_diS	Display orientation	BooleanT	Read Write	1	False	16	6	false		
☐	552	3	V_diS	Update rate	UIntegerT	Read Write	6	False	16	0	2		
☐	554		V_coLr	coLr	UIntegerT	Read Write	8	False	8	0	2		Assignment of the
☐	555		V_cFH	cFH	IntegerT	Read Write	16	False	16	0	512		Upper value for
☐	556		V_cFL	cFL	IntegerT	Read Write	16	False	16	0	256		Lower value for
☐	580		V_ou1_rPM	ou1_RPM	UIntegerT	Read Write	8	False	8	0	3		Output
☐	583		V_SP_FH1	SP_FH1	IntegerT	Read Write	16	False	16	0	5000		Switch point 1,
☐	584		V_rP_FL1	rP_FL1	IntegerT	Read Write	16	False	16	0	4000		Reset point 1,

OK   Cancel   Insert IODD   Delete IODD

Figure 8: "Device Function - Variables" section

The meanings of the fields are:

- In the field "**Index**" the Index of the IO-Link parameter is defined;
- In the field "**SubIndex**" the Subindex of the IO-Link parameter is defined;
- In the field "**Id**" the Id of the IO-Link parameter is defined;
- In the field "**Name**" the name of the IO-Link parameter is defined;
- In the field "**Type**" the data format of the IO-Link parameter is defined;
- In the field "**Access**" the access type of the IO-Link parameter is defined;
- In the field "**Length**" the bit length of the IO-Link parameter is defined;
- In the field "**SindAccSupp**" the value of subindexAccessSupported attribute of the IO-Link parameter is defined;
- In the field "**TotBitLen**" the bit length of the array to which the IO-Link parameter refers is defined;

- In the field "**BitOff**" the bit offset of the IO-Link parameter is defined;
- In the field "**Default**" the default value of the IO-Link parameter is defined;
- In the field "**Value**" the starting value of the IO-Link parameter is defined;
- In the field "**Description**" a description of the IO-Link parameter is defined.

The "I/O Options" section is used to define how linking the data from IO-Link pin 2 and pin 4 to EtherCAT side (Fig. 9).

Name	Access	Position	Start Bit	Invert	Menmonic
Pin 2	Read Only	5	0	☑	
Pin 4	Write	6	0	☐	

OK   Cancel   Insert IODD   Delete IODD

Figure 9: "I/O Options" section
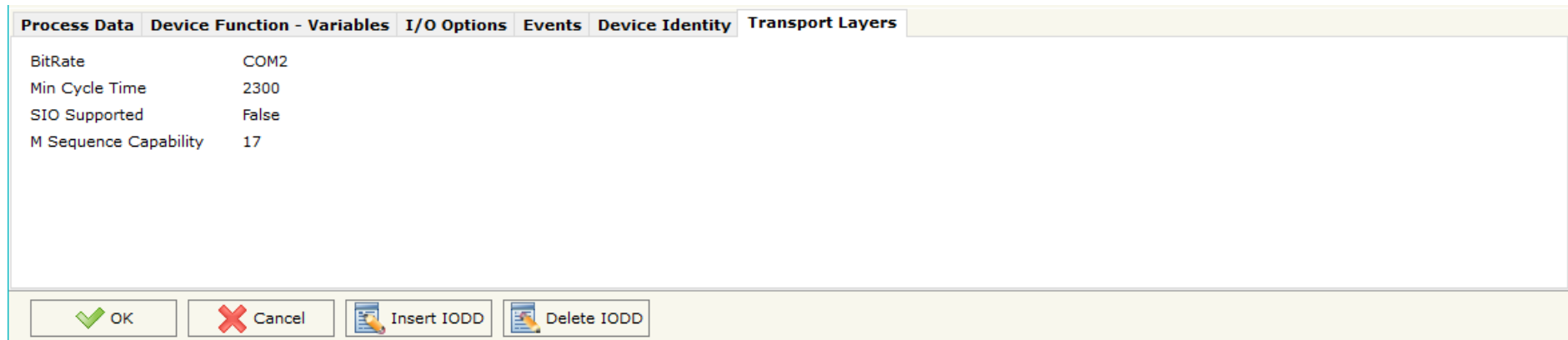
The meanings of the fields are:

- In the field "**Name**" the name of the IO-Link pin is defined;
- In the field "**Access**" the access of the IO-Link pin is defined;
- In the field "**Position**" the starting byte of the internal memory arrays where mapping/getting the value is defined;
- In the field "**Start Bit**" the starting bit of the byte of the field "Position" is defined.
- If the field "**Invert**" the value to map/get is inverted;
- In the field "**Mnemonic**" a description of the variable is defined.

Note:
    IO-Link pin 2 can only be read and IO-LINK pin 4 can be defined if "Pin 4 Mode" is set to "DIn" or "DOut" in "List of IO-Link Channel" section.

The "Events" section is used to define the IO-LINK events to map on EtherCAT side (Fig. 10).
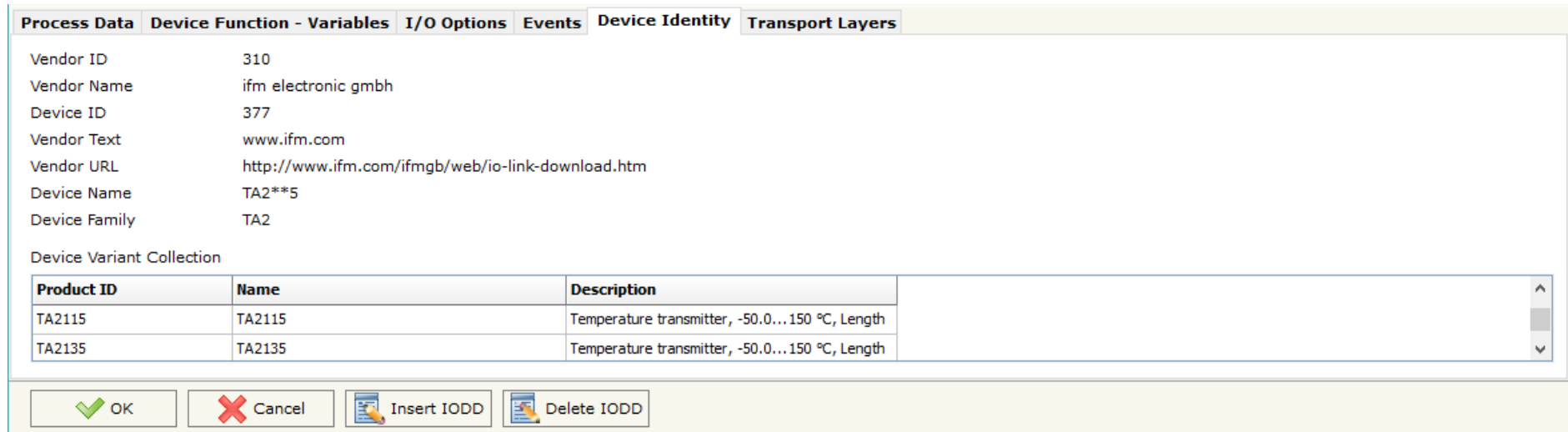
Enable	Code	Name	Type	TimeOut	Position	Start Bit	Menmonic
☑	16928	Device temperature under-run	Warning	2000	3	0	
☑	36016	nEA	Warning	2000	3	1	
☑	36017	fAr	Warning	2000	3	2	
☑	36020	+	Error	2000	3	3	
☑	36021	-	Error	2000	3	4	
☑	36004	ErP	Warning	2000	3	5	
☑	36350	Test Event 1	Warning	2000	3	6	
☑	36351	Test Event 2	Warning	2000	3	7	

Figure 10: "Events" section

The meanings of the fields are:

- In the field "**Code**" the code of the IO-Link event is defined;
- In the field "**Name**" the name of the IO-Link event is defined;
- In the field "**Type**" the type of the IO-Link event is defined;
- In the field "**TimeOut**" the duration of the IO-Link event after its activation is defined;
- In the field "**Position**" the starting byte of the internal memory arrays where mapping/getting the value is defined;
- In the field "**Start Bit**" the starting bit of the byte of the field "Position" is defined;
- In the field "**Mnemonic**" a description of the variable is defined.

In "Device Identity" section (Fig.11) and "Transport Identity" section (Fig. 12), the main features of the selected IO-Link device are reported. These characteristics are read from the IODD file.

| Process Data | Device Function - Variables | I/O Options | Events | **Device Identity** | Transport Layers |

Vendor ID   310
Vendor Name   ifm electronic gmbh
Device ID   377
Vendor Text   www.ifm.com
Vendor URL   http://www.ifm.com/ifmgb/web/io-link-download.htm
Device Name   TA2**5
Device Family   TA2

Device Variant Collection

Product ID	Name	Description
TA2115	TA2115	Temperature transmitter, -50.0...150 °C, Length
TA2135	TA2135	Temperature transmitter, -50.0...150 °C, Length

✔ OK   ✖ Cancel   Insert IODD   Delete IODD

Figure 11: "Transport Layers" section

| Process Data | Device Function - Variables | I/O Options | Events | Device Identity | **Transport Layers** |

BitRate   COM2
Min Cycle Time   2300
SIO Supported   False
M Sequence Capability 17

✔ OK   ✖ Cancel   Insert IODD   Delete IODD

Figure 12: "Device Identity" section

ETHERCAT SET ACCESS:

By Pressing the "**EtherCAT Set Access**" button from the main window for SW67879 (Fig. 2) the window "EtherCAT Slave Set Access" appears (Fig. 13).
This section is used to define the EtherCAT variables readable by the EtherCAT Master (Slave To Master) and the EtherCAT variables writeable by the EtherCAT Master (Master To Slave).

<u>SLAVE TO MASTER</u>
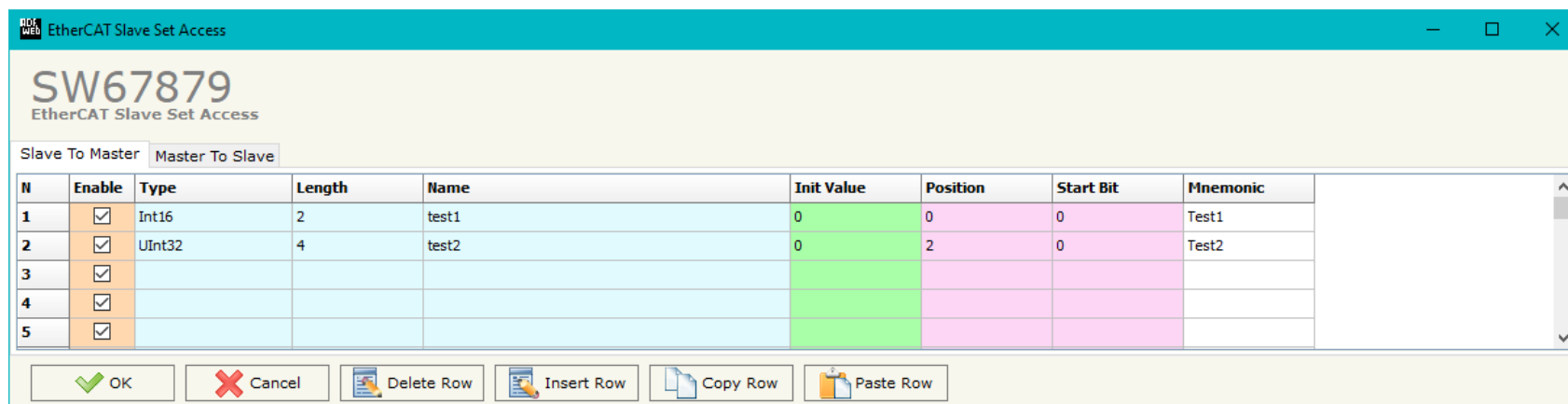
Figure 13a: "EtherCAT Slave Set Access → Slave To Master"

The means of the fields are:

+ If the field "**Enable**" is checked, the EtherCAT variable is enabled;
+ In the field "**Type**" the data format of the EtherCAT variable is defined;
+ In the field "**Lenght**" the dimension of the EtherCAT variable is defined;
+ In the field "**Name**" the name of the EtherCAT variable is defined;
+ In the field "**Init Value**" the default value of the EtherCAT variable is defined;
+ In the field "**Position**" the starting address of the EtherCAT array where the variable is mapped is defined;
+ In the field "**Start Bit**" the starting bit of the selected Position where the variable is mapped is defined;
+ In the field "**Mnemonic**" a description of the variable is defined.

MASTER TO SLAVE
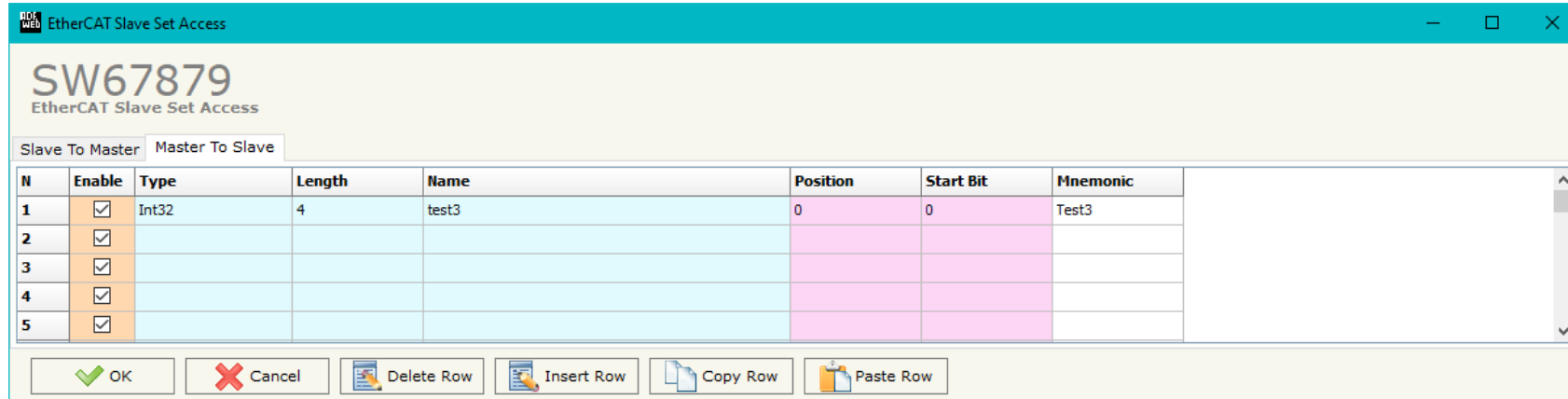
Figure 13b: "EtherCAT Slave Set Access → Master To Slave"

The means of the fields are:

➔ If the field "**Enable**" is checked, the EtherCAT variable is enabled;

➔ In the field "**Type**" the data format of the EtherCAT variable is defined;

➔ In the field "**Lenght**" the dimension of the EtherCAT variable is defined;

➔ In the field "**Name**" the name of the EtherCAT variable is defined;

➔ In the field "**Position**" the starting address of the EtherCAT array where the variable is mapped is defined;

➔ In the field "**Start Bit**" the starting bit of the selected Position where the variable is mapped is defined;

➔ In the field "**Mnemonic**" a description of the variable is defined.

ETHERCAT ESI FILE:

By pressing the "**EtherCAT ESI File**" button it is possible to save the ESI file for the EtherCAT side of the converter.
The ESI file is used to configure the EtherCAT Master.

UPDATE DEVICE:

By pressing the "**Update Device**" button, it is possible to load the created Configuration into the device; and also the Firmware, if necessary. This by using the Ethernet port.

If you don't know the actual IP address of the device, you have to use this procedure:

- Turn OFF the Device;
- Put Dip1 of 'Dip-Switch A' in ON position;
- Turn ON the device
- Connect the Ethernet cable;
- Insert the IP "**192.168.2.205**";
- Select which operations you want to do;
- Press the "**Execute update firmware**" button to start the upload;
- When all the operations are "OK" turn OFF the Device;
- Put Dip1 of 'Dip-Switch A' in OFF position;
- Turn ON the device.

If you know the actual IP address of the device, you have to use this procedure:

- Turn ON the Device with the Ethernet cable inserted;
- Insert the actual IP of the Converter;
- Select which operations you want to do;
- Press the "**Execute update firmware**" button to start the upload;
- When all the operations are "OK" the device automatically goes at Normal Mode.

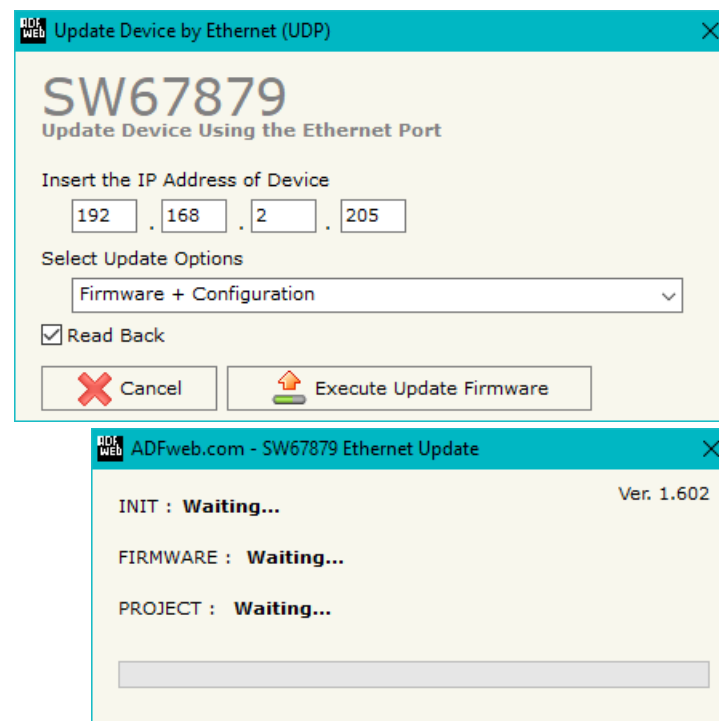At this point the configuration/firmware on the device is correctly updated.

Figure 14: "Update device" windows

Note:
When you receive the device, for the first time, you also have to update the Firmware in the HD67879 device.

Warning:
If Fig. 15 appears when you try to do the Update try these points before seeking assistance:

- Try to repeat the operations for the updating;
- Try with another PC;
- Try to restart the PC;
- Check the LAN settings;
- f you are using the program inside a Virtual Machine, try to use in the main Operating System;
- If you are using Windows Seven, Vista, 8 or 10 make sure that you have the administrator privileges;
- In case you have to program more than one device, using the "UDP Update", you have to cancel the ARP table every time you connect a new device on Ethernet. For do this you have to launch the "Command Prompt" and write the command "arp -d". Pay attention that with Windows Vista, Seven, 8, 10 you have to launch the "Command Prompt" with Administrator Rights;
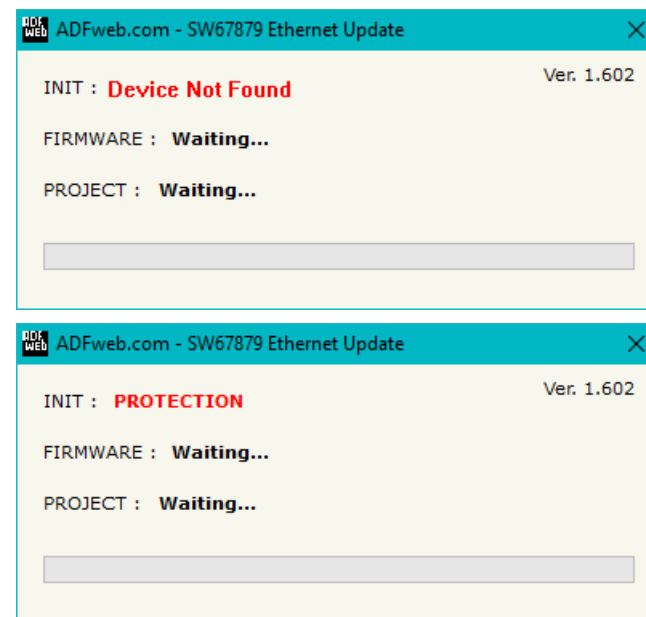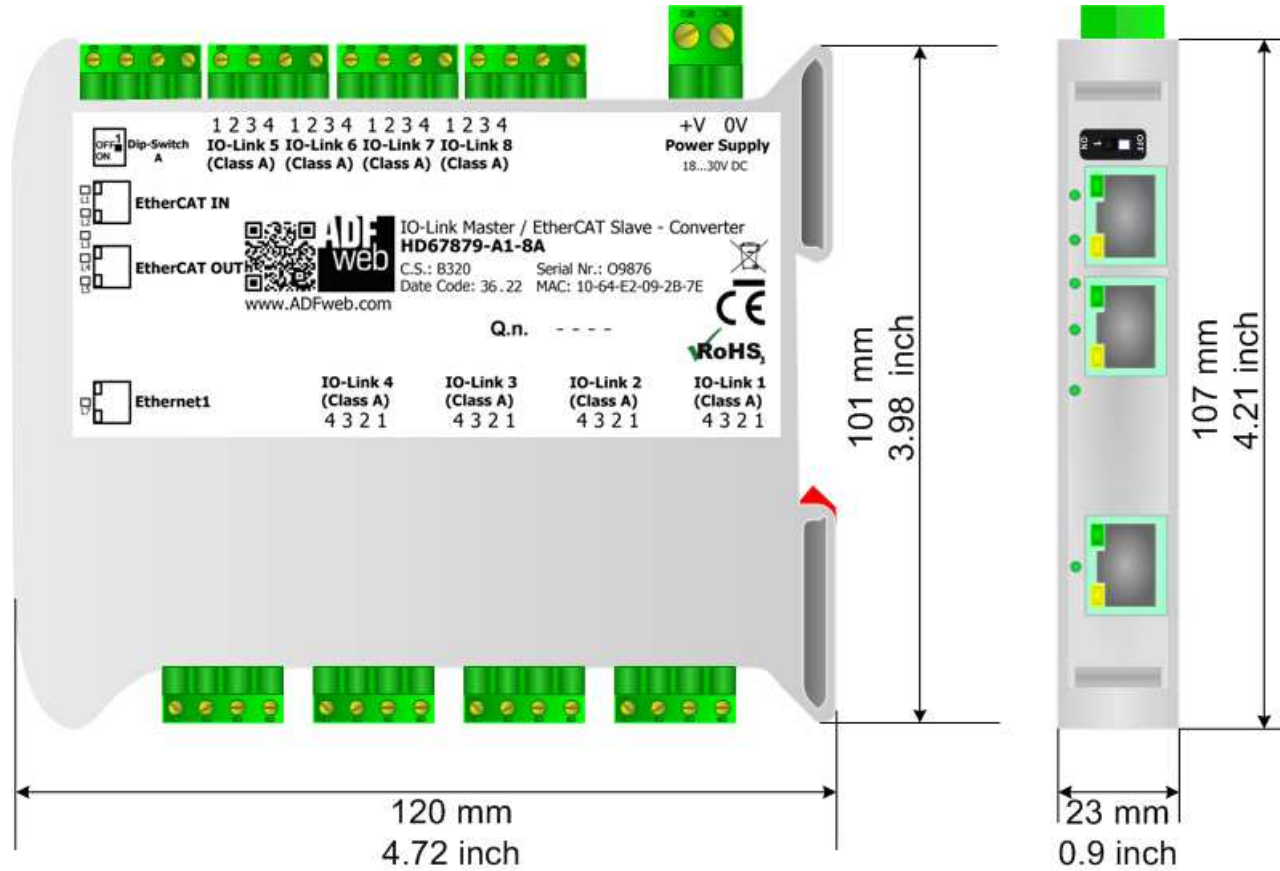- Pay attention at Firewall lock.

Figure 15: "Error" window

Warning:
In the case of HD67879 you have to use the software "SW67879": www.adfweb.com\download\filefold\SW67879.zip.

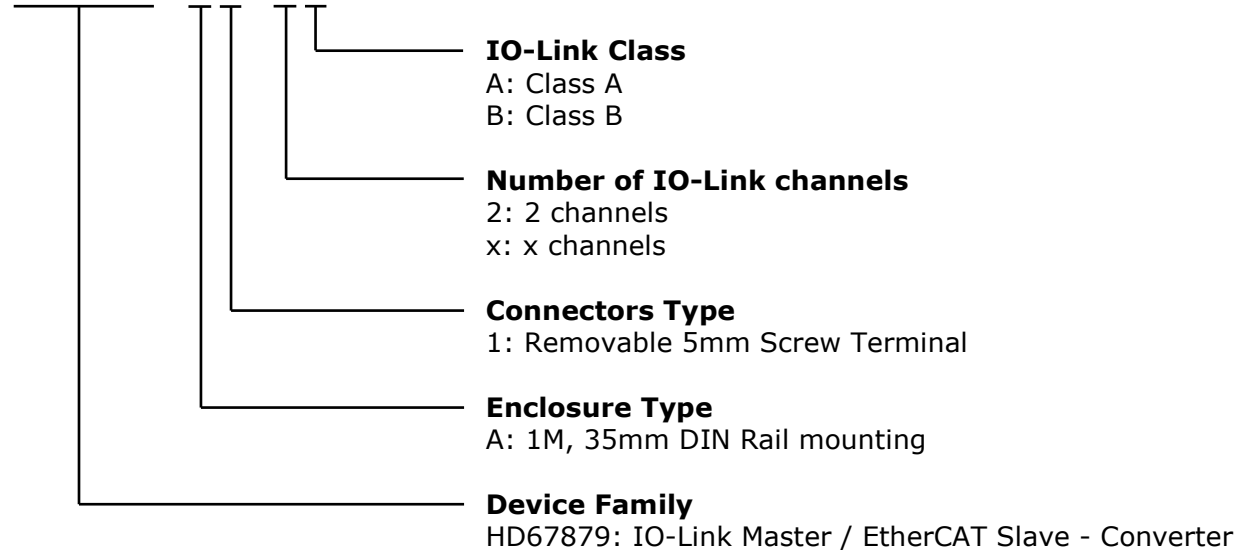**MECHANICAL DIMENSIONS:**

Housing: PVC
Weight: 200g (Approx)

Figure 16: Mechanical dimensions scheme for HD67879-A1-xx

ORDERING INFORMATIONS:

The ordering part number is formed by a valid combination of the following:

HD67879 – A 1 – x x

IO-Link Class
A: Class A
B: Class B

Number of IO-Link channels
2: 2 channels
x: x channels

Connectors Type
1: Removable 5mm Screw Terminal

Enclosure Type
A: 1M, 35mm DIN Rail mounting

Device Family
HD67879: IO-Link Master / EtherCAT Slave - Converter

Order Code:	**HD67879-A1-2A**	-	IO-Link Master / EtherCAT Slave – Converter (IO-Link ports: 2 x Class A)
Order Code:	**HD67879-A1-4A**	-	IO-Link Master / EtherCAT Slave – Converter (IO-Link ports: 4 x Class A)
Order Code:	**HD67879-A1-2B**	-	IO-Link Master / EtherCAT Slave – Converter (IO-Link ports: 2 x Class B)
Order Code:	**HD67879-A1-2A-2B**	-	IO-Link Master / EtherCAT Slave – Converter (IO-Link ports: 2 x Class A and 2 x Class B)
Order Code:	**HD67879-A1-4B**	-	IO-Link Master / EtherCAT Slave – Converter (IO-Link ports: 4 x Class B)
Order Code:	**HD67879-A1-4A-4B**	-	IO-Link Master / EtherCAT Slave – Converter (IO-Link ports: 4 x Class A and 4 x Class B)
Order Code:	**HD67879-A1-8A**	-	IO-Link Master / EtherCAT Slave – Converter (IO-Link ports: 8 x Class A)

ACCESSORIES:

Order Code: **AC34011**   -   Rail DIN - Power Supply 220/240V AC 50/60Hz – 12 V DC

Order Code: **AC34012**   -   Rail DIN - Power Supply 220/240V AC 50/60Hz – 24 V DC

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OTHER REGULATIONS AND STANDARDS:

WEEE INFORMATION

Disposal of old electrical and electronic equipment (as in the European Union and other European countries with separate collection systems).

This symbol on the product or on its packaging indicates that this product may not be treated as household rubbish. Instead, it should be taken to an applicable collection point for the recycling of electrical and electronic equipment. If the product is disposed correctly, you will help prevent potential negative environmental factors and impact of human health, which could otherwise be caused by inappropriate disposal. The recycling of materials will help to conserve natural resources. For more information about recycling this product, please contact your local city office, your household waste disposal service or the shop where you purchased the product.

RESTRICTION OF HAZARDOUS SUBSTANCES DIRECTIVE

The device respects the 2002/95/EC Directive on the restriction of the use of certain hazardous substances in electrical and electronic equipment (commonly referred to as Restriction of Hazardous Substances Directive or RoHS).

CE MARKING

The product conforms with the essential requirements of the applicable EC directives.

ADFweb.com Srl – IT31010 – Mareno – Treviso   INFO: www.adfweb.com   Phone +39.0438.30.91.31

WARRANTIES AND TECHNICAL SUPPORT:

For fast and easy technical support for your ADFweb.com SRL products, consult our internet support at www.adfweb.com.
Otherwise contact us at the address support@adfweb.com

RETURN POLICY:

If while using your product you have any problem and you wish to exchange or repair it, please do the following:

+ Obtain a Product Return Number (PRN) from our internet support at www.adfweb.com. Together with the request, you need to provide detailed information about the problem.
+ Send the product to the address provided with the PRN, having prepaid the shipping costs (shipment costs billed to us will not be accepted).

If the product is within the warranty of twelve months, it will be repaired or exchanged and returned within three weeks. If the product is no longer under warranty, you will receive a repair estimate.